The Role of Abduction in Logic Programming

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Abstract

This paper is a survey and critical overview of recent work on the extension of Logic Programming to perform Abductive Reasoning (Abductive Logic Programming). It updates the earlier paper “Abductive Logic Programming” [88]. We outline the general framework of Abduction and its applications to Knowledge Assimilation and Default Reasoning; we describe the argumentation-theoretic approach to the use of abduction as an interpretation for Negation as Failure, introduced in the earlier version [88] of this paper; and we present recent work on the generalisation of the argumentation-theoretic approach to provide a framework for default reasoning in general. We also analyse the links between Abduction and Constraint Logic Programming, as well as between Abduction and the extension of Logic Programming obtained by adding a form of explicit negation. Finally we discuss the relation between Abduction and Truth Maintenance.

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1 Introduction

This paper extends and updates our earlier survey and analysis of work on the extension of logic programming to perform abductive reasoning [88]. The purpose of the paper is to provide a critical overview of some of the main research results, in order to develop a common framework for evaluating these results, to identify the main unresolved problems, and to indicate directions for future work. The emphasis is not on technical details but on relationships and common features of different approaches. Some of the main issues we will consider are the contributions that abduction can make to the problems of reasoning with incomplete or negative information, the evolution of knowledge, and the semantics of logic programming and its extensions. We also discuss recent work on the argumentation-theoretic interpretation of abduction, which was introduced in the earlier version of this paper.

The philosopher Pierce first introduced the notion of abduction. In [133] he identified three distinguished forms of reasoning.

**Deduction**, an analytic process based on the application of general rules to particular cases, with the inference of a result.

**Induction**, synthetic reasoning which infers the rule from the case and the result.

**Abduction**, another form of synthetic inference, but of the case from a rule and a result.

Peirce further characterised abduction as the "probational adoption of a hypothesis" as explanation for observed facts (results), according to known laws. "It is however a weak kind of inference, because we cannot say that we believe in the truth of the explanation, but only that it may be true"[133].

Abduction is widely used in common-sense reasoning, for instance in diagnosis, to reason from effect to cause [22, 142]. We consider here an example drawn from [131].

**Example 1.1**

Consider the following theory $T$

\[
\text{grass-is-wet} \leftarrow \text{rained-last-night}
\]

\[
\text{grass-is-wet} \leftarrow \text{sprinkler-was-on}
\]

\[
\text{shoes-are-wet} \leftarrow \text{grass-is-wet}.
\]

If we observe that our shoes are wet, and we want to know why this is so, \{rained-last-night\} is a possible explanation, i.e., a set of hypotheses that together with the explicit knowledge in $T$ implies the given observation. \{sprinkler-was-on\} is another alternative explanation.

Abduction consists of computing such explanations for observations. It is a form of non-monotonic reasoning, because explanations which are consistent with one state of a knowledge base may become inconsistent with new information. In the example above the explanation \text{rained-last-night} may turn out to be false, and the alternative explanation \text{sprinkler-was-on} may be the true cause for the given observation. The existence of multiple explanations is a general characteristic of abductive reasoning, and the selection of "preferred" explanations is an important problem.

1.1 Abduction in logic

Given a set of sentences $T$ (a theory presentation), and a sentence $G$ (observation), to a first approximation, the abductive task can be characterised as the problem of finding a set of sentences $\Delta$ (abductive explanation for $G$) such that:

1. $T \cup \Delta \models G$,  
2. $T \cup \Delta$ is consistent.

This characterisation of abduction is independent of the language in which $T$, $G$ and $\Delta$ are formulated. The logical implication sign $\models$ in (1) can alternatively be replaced by a deduction operator $\vdash$. The consistency requirement in (2) is not explicit in Peirce's more informal characterisation of abduction, but it is a natural further requirement.

In fact, these two conditions (1) and (2) alone are too weak to capture Peirce's notion. In particular, additional restrictions on $\Delta$ are needed to distinguish abductive explanations from inductive generalisations [27]. Moreover, we also need to restrict $\Delta$ so that it conveys some reason why the observations hold, e.g., we do not want to explain one effect in terms of another effect, but only in terms of some cause. For both of these reasons, explanations are often restricted to belong to a special pre-specified, domain-specific class of sentences called abducible. In this paper we will assume that the class of abducibles is always given.

Additional criteria have also been proposed to restrict the number of candidate explanations:

- Once we restrict the hypotheses to belong to a specified set of sentences, we can further restrict, without loss of generality, the hypotheses to atoms (that "name") these sentences which are predicates explicitly indicated as abducible, as shown by Poole [145].

- In section 1.2 we will discuss the use of integrity constraints to reduce the number of possible explanations.

- Additional information can help to discriminate between different explanations, by rendering some of them more appropriate or plausible than others. For example, Satar and Goebel [173] use "crucial literals" to discriminate between two mutually incompatible explanations. When the crucial literals are tested, one of the explanations is rejected. More generally Evans and Kakas [56] use the notion of corroborating to select explanations. An explanation fails to be corroborated if some of its logical consequences are not observed. A related technique is presented by Sergot in [175], where information is obtained from the user during the process of query evaluation.

- Moreover various (domain-specific) criteria of preference can be specified. They impose a (partial) order on the sets of hypotheses which leads to the discrimination of explanations [13, 22, 61, 77, 143, 148, 180].

Cox and Pietrykowski [29] identify other desirable properties of abductive explanations. For instance, an explanation should be basic, i.e., should not be explainable in terms of
other explanations. For instance, in example 1.1 the explanation

\[ \{ \text{grass-is-wet} \} \]

for the observation

\[ \text{shoes-are-wet} \]

is not basic, whereas the alternative explanations

\[ \{ \text{rainy-last-night} \} \]
\[ \{ \text{sprinkler-was-on} \} \]

are.

An explanation should also be minimal, i.e. not subsumed by another one. For example, in example 1.1 the explanation

\[ \{ \text{rainy-last-night, sprinkler-was-on} \} \]

for the observation

\[ \text{shoes-are-wet} \]

is not minimal, while the explanations

\[ \{ \text{rainy-last-night} \} \]
\[ \{ \text{sprinkler-was-on} \} \]

are.

So far we have presented a semantic characterisation of abduction and discussed some heuristics to deal with the multiple explanation problem, but we have not described any proof procedures for computing abduction. Various authors have suggested the use of top-down, goal-oriented computation, based on the use of deduction to drive the generation of abductive hypotheses. Cox and Pietrykowski [29] construct hypotheses from the “dead ends” of linear resolution proofs. Finger and Genesereth [57] generate “deductive solutions to design problems” using the “residue” left behind in resolution proofs. Poole, Goebel and Aleliunas [150] also use linear resolution to generate hypotheses.

In contrast, the ATMS [102] computes abductive explanations bottom-up. The ATMS can be regarded as a form of hyper-resolution, augmented with subsumption, for propositional logic programs [102]. Lamma and Mello [115] have developed an extension of the ATMS for the non-propositional case. Resolution-based techniques for computing abduction have also been developed by Demolombe and Facinas del Cero [31] and Gaifman and Shapiro [64].

Abduction can also be applied to logic programming (LP). A (general) logic program is a set of Horn clauses extended by negation as failure [24], i.e. clauses of the form:

\[ A \leftarrow L_1, \ldots, L_n \]

where each \( L_i \) is either an atom \( A_i \) or its negation \( \neg A_i \), \( A \) is an atom and each variable occurring in the clause is implicitly universally quantified. \( A \) is called the head and \( L_1, \ldots, L_n \) is called the body of the clause. A logic program where each literal \( L_i \) in the body of every clause is atomic is said to be definite.

Abduction can be computed in LP by extending SLD and SLDNF [23, 33, 54, 91, 94, 34, 181]. Instead of failing in a proof when a selected subgoal fails to unify with the head of any rule, the subgoal can be viewed as a hypothesis. This is similar to viewing abducibles as “askable” conditions which are treated as qualifications to answers to queries [175]. In the same way that it is useful to distinguish a subset of all predicates as abducible, it is useful to distinguish certain predicates as abducible. In fact, it is generally convenient to choose, as abducible predicates, ones which are not conclusions of any clause. As we shall remark at the beginning of section 5, this restriction can be imposed without loss of generality, and has the added advantage of ensuring that all explanations will be basic.

Abductive explanations computed in LP are guaranteed to be minimal, unless the program itself encodes non-minimal explanations. For example, in the propositional logic program

\[
\begin{align*}
 p & \leftarrow q \\
 p & \leftarrow q, r
\end{align*}
\]

both the minimal explanation \( \{ q \} \) and the non-minimal explanation \( \{ q, r \} \) are computed for the observation \( p \).

The abductive task for the logic-based approach has been proved to be highly intractable: it is NP-hard even if \( T \) is a set of acyclic [7] propositional definite clauses [174, 48], and is even harder if \( T \) is a set of any propositional clauses [48]. These complexity results hold even if explanations are not required to be minimal. However, the abductive task is tractable for certain more restricted classes of logic programs (see for example [52]).

There are other formalisations of abduction. We mention them for completeness, but in the sequel we will concentrate on the logic-based view previously described.

- Allemand, Tamer, Bylander and Josephson [6] and Reggia [155] present a mathematical characterisation, where abduction is defined over sets of observations and hypotheses, in terms of coverings and parsimony.
- Levesque [117] gives an account of abduction at the “knowledge level”, He characterizes abduction in terms of a (modal) logic of beliefs, and shows how the logic-based approach to abduction can be understood in terms of a particular kind of belief.

In the previous discussion we have briefly described both semantics and proof procedures for abduction. The relationship between semantics and proof procedures can be understood as a special case of the relationship between program specifications and programs. A program specification characterises what is the intended result expected from the execution of the program. In the same way semantics can be viewed as an abstraction.

\[ ^{1}\text{In the sequel we will represent negation as failure as \( \neg \).} \]
ossibly non-constructive definition of what is to be computed by the proof procedure. From this point of view, semantics is not so much concerned with explicating meaning in terms of truth and falsity, as it is with providing an abstract specification which “declaratively” expresses what we want to compute. This specification view of semantics is effectively the one adopted in most recent work on the semantics of LP, which restricts interpretations to Herbrand interpretations. The restriction to Herbrand interpretations means that interpretations are purely syntactic objects, which have no bearing on the correspondence between language and “reality”. A purely syntactic view of semantics, based upon the notion of knowledge assimilation described in section 2 below, is developed in [116].

One important alternative way to specify the semantics of a language, which will be used in the sequel, is through the translation of sentences expressed in one language into sentences of another language, whose semantics is already well understood. For example if we have a sentence in a typed logic language of the form “there exists an object of type t such that the property p holds” we can translate this into a sentence of the form \( \exists x (p(x) \land t(x)) \), where \( t \) is a new predicate to represent the type \( t \), whose semantics is then given by the familiar semantics of first-order logic. Similarly the typed logic sentence “for all objects of type t the property p holds” becomes the sentence \( \forall x (p(x) \equiv t(x)) \).

Hence instead of developing a new semantics for the typed logic language, we apply the translation and use the existing semantics of first-order logic.

1.2 Integrity Constraints

Abduction as presented so far can be restricted by the use of integrity constraints. Integrity constraints are useful to avoid unintended updates to a database or knowledge base. They can also be used to represent desired properties of a program [116].

The concept of integrity constraints first arose in the field of databases and to a lesser extent in the field of AI knowledge representation. The basic idea is that only certain knowledge base states are considered acceptable, and an integrity constraint is meant to enforce these legal states. When abduction is used to perform updates (see section 2), we can use integrity constraints to reject abductive explanations.

Given a set of integrity constraints, \( I \), of first-order closed formulae, the second condition (2) of the semantic definition of abduction (see section 1.1) can be replaced by:

\[
(2') \quad T \cup \Delta \text{ satisfies } I.
\]

As previously mentioned, we also restrict \( \Delta \) to consist of atoms drawn from predicates explicitly indicated as abducible. Until the discussion in section 5.7, we further restrict \( \Delta \) to consist of variable-free atomic sentences. In the sequel an abductive framework will be given as a triple \( (T, A, I) \), where \( T \) is a theory, \( A \) is the set of abducible predicates, i.e. \( \Delta \subseteq A \) \(^2\) and \( I \) is a set of integrity constraints.

There are several ways to define what it means for a knowledge base \( KB (T \cup \Delta \text{ in our case}) \) to satisfy an integrity constraint \( \phi \) (in our framework \( \phi \in I \)). The consistency view requires that:

\[
KB \text{ satisfies } \phi \text{ if } KB \cup \phi \text{ is consistent}.
\]

Alternatively the theoremhood view requires that:

\[
KB \text{ satisfies } \phi \text{ if } KB \models \phi.
\]

These definitions have been proposed in the case where the theory is a logic program \( P \) by Kowalski and Sadri [165] and Lloyd and Topor [118] respectively, where \( KB \) is the Clark completion [21] of \( P \).

Another view of integrity constraints [85, 90, 107, 160, 161] regards these as epistemic or meta-level statements about the content of the database. In this case the integrity constraints are understood as statements at a different level from those in the knowledge base. They specify what must be true about the knowledge base rather than what is true about the world modelled by the knowledge base. When later we consider abduction in LP (see sections 4,5), integrity satisfaction will be understood in a sense which is stronger than consistency, weaker than theoremhood, and arguably similar to the epistemic or meta-level view.

For each such semantics, we have a specification of the integrity checking problem. Although the different views of integrity satisfaction are conceptually very different, the integrity checking procedures based upon these views are not very different in practice (e.g. [30, 165, 118]). They are mainly concerned with avoiding the inefficiency which arises if all the integrity constraints are retested after each update. A common idea of all these procedures is to render integrity checking more efficient by exploiting the assumption that the database before the update satisfies the integrity constraints, and therefore if integrity constraints are violated after the update, this violation should depend upon the update itself. In [165] this assumption is exploited by reasoning forward from the updates. This idea is exploited for the purpose of checking the satisfaction of abductive hypotheses in [54, 93, 94]. Although this procedure was originally formulated for the consistency view of constraint satisfaction, it has proved equally appropriate for the semantics of integrity constraints in abductive logic programming.

1.3 Applications

In this section we briefly describe some of the applications of abduction in AI. In general, abduction is appropriate for reasoning with incomplete information. The generation of abducibles to solve a top-level goal can be viewed as the addition of new information to make incomplete information more complete.

Abduction can be used to generate causal explanations for fault diagnosis (see for example [25, 151]). In medical diagnosis, for example, the candidate hypotheses are the possible causes (diseases), and the observations are the symptoms to be explained [166, 153]. Abduction can also be used for model-based diagnosis [51, 128]. In this case the theory describes the “normal” behaviour of the system, and the task is to find a set of hypotheses of the form “some component A is not normal” that explains why the behaviour of
Abduction can be used to perform high level vision [1]. The hypotheses are the objects data) in to a theory (or knowledge base) [2]. There are four possible deductive relationships between the current knowledge base (KB), the new information, and the new KB which arises as a result [10, 14].

1. The new information is already deducible from the current KB. The new KB is KB χ3 KB can be decomposed into two parts. One part KB χ1 is identical with the current KB, the other part KB χ2 contains the new information.

2. The new information is already deducible from the current KB. The new KB is KB χ3 KB can be decomposed into two parts. One part KB χ2 is identical with the current KB, the other part KB χ1 contains the new information.

3. The new information is independent from the current KB. The new KB is KB χ3 KB can be decomposed into two parts. One part KB χ1 is identical with the current KB, the other part KB χ2 contains the new information.

4. The new information is independent from the current KB. The new KB is KB χ3 KB can be decomposed into two parts. One part KB χ2 is identical with the current KB, the other part KB χ1 contains the new information.

In case (4) the KB can, alternatively, be generated from an abstraction for the new datum. Various motivations can be given for the abstraction of an abductive explanation instead of a direct causal interpretation [11]. The abstraction of information can be used to fill in gaps in the understanding of causality. The assimilation of information as a way of assimilating new data to an existing KB is a case for instance for the formulation of explanatory reasoning in the Event Calculus [12, 13, 14, 15].

Example 2.1

The simplified version of the Event Calculus we consider contains an axioms which expresses the persistence of a property P from time Tt to time Tt+1 is initiated by an event E and is forced by the particular way in which the knowledge is represented in the theory. This has the additional property that the new KB will imply that the property holds until an event E occurs, as illustrated by the following example.

New information that a property holds at a particular time point can be assimilated by adding an explanation in terms of the happening of some event that is initiated by the property. An explanation can then be assimilated to the KB (or the KB) in greater detail below. The assimilation of a new datum can be performed by adding the new information to the current KB. In this way, we can also have as an explanation for the new datum a KB that is consistent with the current KB. In particular, the use of abductive explanations (for example, in natural language understanding or in diagnosis) the assimilation of information naturally demands an explanation. Pople [15] argues that the use of abduction avoids the need to develop a non-classical, non-monotonic logic for default reasoning. The abductive explanations are interpreted as satisfying the update request.

The idea of abduction can be used to perform high level vision [1]. The hypotheses are the objects data into a theory (or knowledge base) [2]. There are four possible deductive relationships between the current knowledge base (KB), the new information, and the new KB which arises as a result [10, 14].

1. The new information is already deducible from the current KB. The new KB is KB χ3 KB can be decomposed into two parts. One part KB χ1 is identical with the current KB, the other part KB χ2 contains the new information.

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3. The new information is independent from the current KB. The new KB is KB χ3 KB can be decomposed into two parts. One part KB χ1 is identical with the current KB, the other part KB χ2 contains the new information.

4. The new information is independent from the current KB. The new KB is KB χ3 KB can be decomposed into two parts. One part KB χ2 is identical with the current KB, the other part KB χ1 contains the new information.
from a time $T_1$ to a later time $T_2$ if an event $E$ happens at a time $T$ between $T_1$ and $T_2$ such that $E$ terminates $P$ is expressed by the following integrity constraint:

$$-\left[ \text{persists}(T_1, P, T_2) \land \text{happens}(E, T) \land \text{terminates}(E, P, T) \land T_1 < T < T_2 \right].$$

Assimilating new information by adding explanations that satisfy the integrity constraints has the further effect of resolving conflicts between the current KB and the new information [89, 176]. For example, suppose that KB contains the facts $^3$

- $\text{happens}(\text{takesLook}(\text{mary}, t_0))$
- $\text{initiates}(\text{takesLook}(X, \text{hasLook}(X)))$
- $\text{terminates}(\text{givesLook}(X, Y), \text{hasLook}(X))$
- $\text{initiates}(\text{givesLook}(X, Y), \text{hasLook}(Y))$

Then, given $t_0 < t_1 < t_2$, the persistence axiom predicts $\text{holdsAt}(\text{hasLook}(\text{mary}, t_1))$ by assuming $\text{persists}(t_0, \text{hasLook}(\text{mary}, t_1))$, and $\text{holdsAt}(\text{hasLook}(\text{mary}, t_2))$ by assuming $\text{persists}(t_0, \text{hasLook}(\text{mary}, t_2))$. Both these assumptions are consistent with the integrity constraint. Suppose now that the new information $\text{holdsAt}(\text{hasLook}(\text{john}, t_2))$ is added to KB. This conflicts with the prediction $\text{holdsAt}(\text{hasLook}(\text{mary}, t_2))$. However, the new information can be assimilated by adding to KB the hypotheses $\text{happens}(\text{givesLook}(\text{mary}, \text{john}, t_1))$ and $\text{persists}(t_1, \text{hasLook}(\text{john}, t_2))$ and by retracting the hypothesis $\text{persists}(t_0, \text{hasLook}(\text{mary}, t_2))$. Therefore, the earlier prediction $\text{holdsAt}(\text{hasLook}(\text{mary}, t_2))$ can no longer be derived from the new KB.

Note that in this example the hypothesis $\text{happens}(\text{givesLook}(\text{mary}, \text{john}, t_1))$ can be added to KB since it does not violate the further integrity constraint

$$-\left[ \text{happens}(E, T) \land \text{precondition}(E, T, P) \land \sim \text{holdsAt}(P, T) \right]$$

expressing that an event $E$ cannot happen at a time $T$ if the preconditions $P$ of $E$ do not hold at time $T$. In this example, we may assume that KB also contains the fact $\text{precondition}(\text{givesLook}(X, Y), \text{hasLook}(X))$.

Once a hypothesis has been generated as an explanation for an external datum, it itself needs to be assimilated into the KB. In the simplest situation, the explanation is just added to the KB, i.e. only case (4) applies without further abduction. Case (1) doesn't apply, if abductive explanations are required to be basic. However case (2) may apply, and can be particularly useful for discriminating between alternative explanations for the new information. For instance we may prefer a set of hypotheses which entails information already in the KB, i.e. hypotheses that render the KB as “compact” as possible.

**Example 2.2**

Suppose the current KB contains

- $p \leftarrow q$
- $p$
- $r \leftarrow q$
- $r \leftarrow s$

Suppose the view update

`insert sibling(mary, bob)`

is given. This can be translated into either of the two minimal updates

- `insert father(john, bob)`
- `insert mother(jane, bob)`

and $r$ is the new datum to be assimilated. The explanation $\{q\}$ is preferable to the explanation $\{s\}$, because $q$ implies both $r$ and $p$, but $s$ only implies $r$. Namely, the explanation $\{q\}$ is more relevant.

Notice however that the use of case (2) to remove redundant information can cause problems later. If we need to retract previously inserted information, enailed information which is no longer explicitly in the KB might be lost.

It is interesting to note that case (3) can be used to check the integrity of abductive hypotheses generated in case (4).

Any violation of integrity detected in case (3) can be remedied in several ways [105]. The new input can be retracted as in conventional databases. Alternatively the new input can be upheld and some other assumptions can be withdrawn. This is the case with **view updates**. The task of translating the update request on the view predicates to an equivalent update on the extensional part (as in case (4) of KA) is achieved by finding an abductive explanation for the update in terms of variable-free instances of extensional predicates [91]. Any violation of integrity is dealt with by changing the extensional part of the database.

**Example 2.3**

Suppose the current KB consists of the clauses

- $\text{sibling}(X, Y) \leftarrow \text{parent}(Z, X), \text{parent}(Z, Y)$
- $\text{parent}(X, Y) \leftarrow \text{father}(X, Y)$
- $\text{parent}(X, Y) \leftarrow \text{mother}(X, Y)$
- $\text{father}(\text{john}, \text{mary})$
- $\text{mother}(\text{jane}, \text{mary})$

together with the integrity constraints

- $X = Y \leftarrow \text{father}(X, Z), \text{father}(Y, Z)$
- $X = Y \leftarrow \text{mother}(X, Z), \text{mother}(Y, Z)$
- $X \neq Y \leftarrow \text{mother}(X, Z), \text{father}(Y, W)$

where $\text{sibling}$ and $\text{parent}$ are view predicates, $\text{father}$ and $\text{mother}$ are extensional, and $=, \neq$ are “built-in” predicates such that

- $X = X$ and
- $s \neq t$ for all distinct variable-free terms $s$ and $t$.

Suppose the view update

`insert sibling(mary, bob)`

is given. This can be translated into either of the two minimal updates

- `insert father(john, bob)`
- `insert mother(jane, bob)`

Note that here KB contains a definition for the abducible predicate $\text{happens}$. In section 5 we will see that new predicates and clauses can be added to KB so that abducible predicates have no definitions in the transformed KB.
on the extensional part of the KB. Both of these updates satisfy the integrity constraints. However, only the first update satisfies the integrity constraints if we are given the further update

\[ \text{insert} \ \text{mother}(\text{sus, bob}). \]

The general problem of belief revision has been studied formally in [65, 128, 120, 37]. Gärdenfors proposes a set of axioms for rational belief revision containing such constraints on the new theory as “no change should occur to the theory when trying to delete a fact that is not already present” and “the result of revision should not depend on the syntactic form of the new data”. These axioms ensure that there is always a unique way of performing belief revision. However Doyle [37] argues that, for applications in AI, this uniqueness property is too strong. He proposes instead the notion of “economic rationality”, in which the revised sets of beliefs are optimal, but not necessarily unique, with respect to a set of preference criteria on the possible belief states. This notion has been used to study the evolution of databases by means of updates [86]. It should be noted that the use of abduction to perform belief revision in the view update case also allows results which are not unique, as illustrated in example 2.3. Aravindan and Dung [8] have given an abductive characterisation of rational belief revision and have applied this result to formulate belief revision postulates for the view update problem.

A logic-based theory of the assimilation of new information has also been developed in the Relevance Theory of Sperber and Wilson [1]: with special attention to natural language understanding. Gabbay, Kempson and Pitts [63] have investigated how abductive reasoning and relevance theory can be integrated to choose between different abductive interpretations of a natural language discourse.

KA and belief revision are also related to truth maintenance systems. We will discuss truth maintenance and its relationship with abduction in section 8.

3 Default Reasoning viewed as Abduction

Default reasoning concerns the application of general rules to draw conclusions provided the application of the rules does not result in contradictions. Given, for example, the general rules “birds fly” and “penguins are birds that do not fly” and the only fact about Tweety that Tweety is a bird, we can derive the default conclusion that Tweety flies. However, if we are now given the extra information that Tweety is a penguin, we can also conclude that Tweety does not fly. In ordinary, common sense reasoning, the rule that penguins do not fly has priority over the rule that birds fly, and consequently this new conclusion that Tweety does not fly causes the original conclusion to be withdrawn.

One of the most important formalisations of default reasoning is the Default Logic of Reiter [1:58]. Reiter separates beliefs into two kinds, ordinary sentences used to express “facts” and default rules of inference used to express general rules. A default rule is an inference rule of the form

\[ \alpha(X) : M_1 \beta_1(X), \ldots, M_n \beta_n(X) \]

\[ \gamma(X) \]

which expresses, for all variable-free instances \( t \) of \( X \), \( \gamma(t) \) can be derived if \( \alpha(t) \) holds and each of \( \beta_i(t) \) is consistent, where \( \alpha(X), \beta_i(X), \gamma(X) \) are first-order formulae. Default rules provide a way of extending an underlying incomplete theory. Different applications of the defaults can yield different extensions.

As already mentioned in section 1, Poole, Goebel and Aleliunas [1:50] and Poole [1:45] propose an alternative formalisation of default reasoning in terms of abduction. Like Reiter, Poole also distinguishes two kinds of beliefs:

- beliefs that belong to a consistent set of first order sentences \( \mathcal{F} \) representing “facts”,
- beliefs that belong to a set of first order formulae \( D \) representing defaults.

Perhaps the most important difference between Poole’s and Reiter’s formalisations is that Poole uses sentences (and formulae) of classical first order logic to express defaults, while Reiter uses rules of inference. Given a Theorist framework \( (\mathcal{F}, D) \), default reasoning can be thought of as theory formation. A new theory is formed by extending the existing theory \( \mathcal{F} \) with a set \( \Delta \) of sentences which are variable-free instances of formulae in \( D \).

The new theory \( \mathcal{F} \cup \Delta \) should be consistent. This process of theory formation is a form of abduction, where variable-free instances of defaults in \( D \) are the candidate abducibles. Poole [1:45] shows that the semantics of the theory formation framework \( (\mathcal{F}, D) \) is equivalent to that of an abductive framework \( (\mathcal{F}, A, \emptyset) \) (see section 1.2) where the default formulae are all atomic. The set of abducibles \( A \) consists of a new predicate

\[ p_a(x) \]

for each default formula

\[ w(x) \]

in \( D \) with free variables \( x \). The new predicate is said to “name” the default. The set \( \mathcal{F} \) is the set \( \mathcal{F} \) augmented with a sentence

\[ \forall x [p_a(X) \rightarrow w(X)] \]

for each default in \( D \).

The theory formation framework and its correspondence with the abductive framework can be illustrated by the flying-birds example.

**Example 3.1**

In this case, the framework \( (\mathcal{F}, D) \) is \^5

\[ \mathcal{F} = \{ \text{penguin}(X) \rightarrow \text{bird}(X) \} \]

\[^5\text{We use the notation } X \text{ to indicate a tuple of variables } x_1, \ldots, x_n \text{ and } t \text{ to represent a tuple of terms } t_1, \ldots, t_n.\]

\[^6\text{Here, we use the conventional notation of first-order logic, rather than LP form. We use } \rightarrow \text{ for the usual implication symbol for first-order logic in contrast with } \rightarrow \text{ for LP. However, as in LP notation, variables occurring in formulae of } \mathcal{F} \text{ are assumed to be universally quantified. Formulae of } D \text{ on the other hand, should be understood as schemata standing for the set of all their variable-free instances.}\]
\[ penguin(X) \rightarrow \neg fly(X), \]
\[ penguin(tweety), \]
\[ bird(john) \]
\[ D = \{ \ bird(X) \rightarrow fly(X) \}. \]

The priority of the rule that penguins do not fly over the rule that birds fly is obtained by regarding the first rule as a fact and the second rule as a default. The atom \( fly(john) \) is a default conclusion which holds in \( \mathcal{F} \cup \Delta \) with
\[ \Delta = \{ \ bird(X) \rightarrow fly(X) \}. \]

We obtain the same conclusion by naming the default (1) by means of a predicate \( birds-fly(X) \), adding to \( \mathcal{F} \) the new “fact”
\[ birds-fly(X) \rightarrow [bird(X) \rightarrow fly(X)] \]
and extending the resulting augmented set of facts \( \mathcal{F}' \) with the set of hypotheses \( \Delta' = \{ birds-fly(john) \} \). On the other hand, the conclusion \( fly(tweety) \) cannot be derived, because the extension
\[ \Delta = \{ \ bird(tweety) \rightarrow fly(tweety) \} \]
is inconsistent with \( \mathcal{F} \), and similarly the extension
\[ \Delta' = \{ birds-fly(tweety) \} \]
is inconsistent with \( \mathcal{F}' \).

Poole shows that normal defaults without prerequisites in Reiter’s default logic
\[ \vdash M\beta(X) \]
\[ \beta(X) \]
can be simulated by Theorist (abduction) simply by making the predicates \( \beta(X) \) abducible. He shows that the default logic extensions in this case are equivalent to maximal sets of variable-free instances of the default formulae \( \beta(X) \) that can consistently be added to the set of facts.

Maximality of abductive hypotheses is a natural requirement for default reasoning, because we want to apply defaults whenever possible. However, maximality is not appropriate for other uses of abductive reasoning. In particular, in diagnosis we are generally interested in explanations which are minimal. Later, in section 5.1 we will distinguish between default and non-default abducibles in the context of abductive logic programming.

In the attempt to use abduction to simulate more general default rules, however, Poole needs to use integrity constraints. The new theory \( \mathcal{F} \cup \Delta \) should be consistent with these constraints. Default rules of the form:
\[ \alpha(X) : M\beta_1(X), \ldots, M\beta_n(X) \]
\[ \gamma(X) \]
are translated into “facts”, which are implications
\[ \alpha(X) \land M_1(X) \land \ldots \land M_n(X) \rightarrow \gamma(X) \]
where \( M_0 \) is a new predicate, and \( M_i(X) \) is a default formula (abducible), for all \( i = 1, \ldots, n \). Integrity constraints
\[ \neg \beta_i(X) \rightarrow \neg M_i(X) \]
are needed to link the new predicates \( M_i \) appropriately with the predicates \( \beta_i \) for all \( i = 1, \ldots, n \). A further integrity constraint
\[ \neg \gamma(X) \rightarrow \neg M_0(X), \]
for any \( i = 1, \ldots, n \), is needed to prevent the application of the contrapositive
\[ \neg \gamma(X) \land M_0(X) \land \ldots \land M_n(X) \rightarrow \neg \alpha(X) \]
of the implication, in the attempt to make the implication behave like an inference rule. This use of integrity constraints is different from their intended use in abductive frameworks as presented in section 1.2.

Poole’s attempted simulation of Reiter’s general default rules is not exact. He presents a number of examples where the two formulations differ and argues that Reiter’s default logic gives counterintuitive results. In fact, many of these examples can be dealt with correctly in certain extensions of default logic, such as Cumulative Default Logic [121], and it is possible to dispute some of the other examples. But, more importantly, there are still other examples where the Theorist approach arguably gives the wrong result. The most important of these is the now notorious Yale shooting problem [73, 74]. This can be reduced to the propositional logic program:
\[ alive-after-load-wait-shoot \leftarrow alive-after-load-wait, \]
\[ \sim abnormal-alive-shoot \]
\[ loaded-after-load-wait \leftarrow loaded-after-load, \]
\[ \sim abnormal-loaded-wait \]
\[ abnormal-alive-shoot \leftarrow loaded-after-load-wait \]
\[ alive-after-load-wait \leftarrow loaded-after-load. \]

As argued in [127], these clauses can be simplified further. First, the facts \( alive-after-load-wait \) and \( loaded-after-load \) can be eliminated by resolving them against the corresponding conditions of the first two clauses, giving
\[ alive-after-load-wait-shoot \leftarrow \sim abnormal-alive-shoot \]
\[ loaded-after-load-wait \leftarrow \sim abnormal-loaded-wait \]
\[ abnormal-alive-shoot \leftarrow loaded-after-load-wait \]

Then the atom \( loaded-after-load-wait \) can be resolved away from the second and third clauses leaving the two clauses
The resulting clauses have the form

\[
\begin{align*}
    p & \leftarrow \sim q \\
    \sim q & \leftarrow r.
\end{align*}
\]

Hanks and McDermott showed, in effect, that the default theory, whose facts consist of

\[
\begin{align*}
    \sim q & \rightarrow p \\
    \sim r & \rightarrow q
\end{align*}
\]

and whose defaults are the normal defaults

\[
\begin{align*}
    : M \sim q & \quad : M \sim r \\
    \sim q & \quad \sim r
\end{align*}
\]

has two extensions: one in which \( \sim r \), and therefore \( q \) holds; and one in which \( \sim q \), and therefore \( p \) holds. The second extension is intuitively incorrect under the intended interpretation. Hanks and McDermott showed that many other approaches to default reasoning give similarly incorrect results. However, Morris [127] showed that the default theory which has no facts but contains the two non-normal defaults

\[
\begin{align*}
    : M \sim q & \quad : M \sim r \\
    \sim q & \quad \sim r
\end{align*}
\]

yields only one extension, containing \( q \), which is the correct result. In contrast, all natural representations of the problem in Theorist give incorrect results.

As Eshghi and Kowalski [53], Evans [55] and Apt and Bezem [7] observe, the Yale shooting problem has the form of a logic program, and interpreting negation in the problem as negation as failure yields only the correct result. This is the case for both the semantics and the proof theory of LP. Moreover, [53] and [88] show how to retain the correct result when negation as failure is interpreted as a form of abduction.

On the other hand, the Theorist framework does overcome the problem that some default theories do not have extensions and hence cannot be given any meaning within Reiter's default logic. In the next section we will see that this problem also occurs in LP, but that it can also be overcome by an abductive treatment of negation as failure. We will also see that the resulting abductive interpretation of negation as failure allows us to regard LP as a hybrid which treats defaults as abducibles in Theorist but treats clauses as inference rules in default logic.

The inference rule interpretation of logic programs, makes LP extended with abduction especially suitable for default reasoning. Integrity constraints can be used, not for preventing application of contrapositives, but for representing negative information and exceptions to defaults.

Example 3.2

The default (1) in the flying-birds example 3.1 can be represented by the logic program

\[
\begin{align*}
    \text{fly}(X) & \leftarrow \text{bird}(X), \text{birds-fly}(X),
\end{align*}
\]

with the abducible predicate \( \text{birds-fly}(X) \). Note that this clause is equivalent to the “fact” (2) obtained by renaming the default (1) in Theorist. The exception can be represented by an integrity constraint:

\[
\begin{align*}
    \sim \text{fly}(X) & \leftarrow \text{penguin}(X).
\end{align*}
\]

The resulting logic program, extended by means of abduction and integrity constraints, gives similar results to the Theorist formulation of example 3.1.

In sections 4, 5 and 6 we will see other ways of performing default reasoning in LP. In section 4 we will introduce negation as failure as a form of abductive reasoning. In section 5 we will discuss abductive logic programming with default and non-default abducibles and domain-specific integrity constraints. In section 6 we will consider an extended LP framework that contains clauses with negative conclusions and avoids the use of explicit integrity constraints in many cases. In section 7 we will present an abstract argumentation-based framework for default reasoning which unifies the treatment of abduction, default logic, LP and several other approaches to default reasoning.

4 Negation as Failure as Abduction

We noted in the previous section that default reasoning can be performed by means of abduction in LP by explicitly introducing abducibles into rules. Default reasoning can also be performed with the use of negation as failure (NAF) [21] in general logic programs. NAF provides a natural and powerful mechanism for performing non-monotonic default and default reasoning. As we have already mentioned, it provides a simple solution to the Yale shooting problem. The abductive interpretation of NAF that we will present below provides further evidence for the suitability of abduction for default reasoning.

To see how NAF can be used for default reasoning, we return to the flying-birds example.

Example 4.1

The NAF formulation differs from the logic program with abduction presented in the last section (example 3.2) by employing a negative condition

\[
\sim \text{abnormal-bird}(X)
\]

instead of a positive abducible condition

\[
\text{birds-fly}(X)
\]

and by employing a positive conclusion

\[
\text{abnormal-bird}(X)
\]
in an ordinary program clause, instead of a negative conclusion

\[ \neg \text{fly}(X) \]

in an integrity constraint. The two predicates \textit{abnormal\textendash bird} and \textit{birds\textendash fly} are opposite to one another. Thus in the NAF formulation the default is expressed by the clause

\[ \text{fly}(X) \leftarrow \text{bird}(X), \neg \text{abnormal\textendash bird}(X) \]

and the exception by the clause

\[ \text{abnormal\textendash bird}(X) \leftarrow \text{penguin}(X). \]

In this example, both the abductive formulation with an integrity constraint and the NAF formulation give the same result. We will see later in section 5.5 that there exists a systematic transformation which replaces positive abducible by NAF and integrity constraints by ordinary clauses. This example can be regarded as an instance of that transformation.

4.1 Logic programs as abductive frameworks

The similarity between abduction and NAF can be used to give an abductive interpretation of NAF. This interpretation was presented in [33] and [51], where negative literals are interpreted as abductive hypotheses that can be assumed to hold provided that, together with the program, they satisfy a canonical set of integrity constraints. A general logic program \( P \) is thereby transformed into an abductive framework \( (P^*, A^*, I^*) \) (see section 1) in the following way:

- A new predicate symbol \( p^* \) (the opposite of \( p \)) is introduced for each \( p \) in \( P \), and \( A^* \) is the set of all these predicates.
- \( P^* \) is \( P \) where each negative literal \( \neg p(t) \) has been replaced by \( p^*(t) \).
- \( I^* \) is a set of all integrity constraints of the form \(^6\)

\[ \forall X \neg [p(X) \land p^*(X)] \text{ and } \forall X [p(X) \lor p^*(X)]. \]

\(^6\)In the original paper the disjunctive integrity constraints were written in the form

\[ \text{Dem}(P^* \cup A^*, p(t)) \lor \text{Dem}(P^* \cup I^*, p^*(t)), \]

where \( t \) is any variable-free term. This formulation makes explicit a particular (meta-level) interpretation of the disjunctive integrity constraint. The simpler form

\[ \forall X [p(X) \lor p^*(X)] \]

is neutral with respect to the interpretation of integrity constraints and allows the meta-level interpretation as a special case.

The semantics of the abductive framework \( (P^*, A^*, I^*) \), in terms of \textit{extensions}\(^7\) \( P^* \cup \Delta \) of \( P^* \), where \( \Delta \subseteq A^* \), gives a semantics for the original program \( P \). A conclusion \( Q \) holds with respect to \( P \) if and only if the query \( Q^* \), obtained by replacing each negative literal \( \neg p(t) \) in \( Q \) by \( p^*(t) \), has an abductive explanation in the framework \( (P^*, A^*, I^*) \). This transformation of \( P \) into \( (P^*, A^*, I^*) \) is an example of the method, described at the end of section 1.1, of giving a semantics to a language by translating it into another language whose semantics is already known.

The integrity constraints in \( I^* \) play a crucial role in capturing the meaning of NAF. The denials express that the newly introduced symbols \( p^* \) are the negations of the corresponding \( p \). They prevent an assumption \( p^*(t) \) if \( p(t) \) holds. On the other hand the disjunctive integrity constraints force a hypothesis \( p^*(t) \) whenever \( p(t) \) does not hold.

Hence we define the meaning of the integrity constraints \( I^* \) as follows. An extension \( P^* \cup \Delta \) of a Horn theory \( P^* \) satisfies \( I^* \) if and only if for every variable-free atom \( p \),

\[ P^* \cup \Delta \nvdash p \lor p^*, \text{ and } P^* \cup \Delta \nvdash p \text{ or } P^* \cup \Delta \nvdash p^*. \]

Eshghi and Kowalski [51] show that there is a one to one correspondence between stable models [68] of \( P \) and abductive extensions of \( P^* \). We recall the definition of stable model.

Let \( P \) be a general logic program, and assume that all the clauses in \( P \) are variable-free.\(^8\) For any set \( M \) of variable-free atoms, let \( P_M \) be the Horn program obtained by deleting from \( P \):

i) each rule that contains a negative literal \( \neg A \), with \( A \in M \),

ii) all negative literals in the remaining rules.

If the minimal (Herbrand) model of \( P_M \) coincides with \( M \), then \( M \) is a \textit{stable model} for \( P \).

The correspondence between the stable model semantics of a program \( P \) and abductive extensions of \( P^* \) is given by:

- For any stable model \( M \) of \( P \), the extension \( P^* \cup \Delta \) satisfies \( I^* \), where \( \Delta = \{ p^* \mid p \text{ is a variable-free atom, } p \notin \Delta \} \).

- For any \( \Delta \) such that \( P^* \cup \Delta \) satisfies \( I^* \), there is a stable model \( M \) of \( P \), where \( M = \{ p \mid p \text{ is a variable-free atom, } p \notin \Delta \} \).

Notice that the disjunctive integrity constraints in the abductive framework correspond to a totality requirement that every atom must be either true or false in the stable model.

\(^7\)This use of the term \"extension\" is different from other uses. For example, in default logic an extension is formally defined to be the deductive closure of a theory \"extended\" by means of the conclusions of default rules. In this paper we also use the term \"extension\" informally (as in example 3.1) to refer to \( \Delta \) alone.

\(^8\)If \( P \) is not variable-free, then it is replaced by the set of all its variable-free instances.
semantics. Several authors have argued that this totality requirement is too strong, because it prevents us from giving a semantics to some programs, for example $p \leftarrow \lnot p$. We would like to be able to assign a semantics to every program in order to have modularity, as otherwise one part of the program can affect the meaning of another unrelated part. We will see below that the disjunctive integrity constraint also causes problems for the implementation of the abductive framework for NAF.

Notice that the semantics of NAF in terms of abductive extensions is syntactic rather than model-theoretic. It is a semantics in the sense that it is a non-constructive specification. Similarly, the stable model semantics, as is clear from its correspondence with abductive extensions, is a semantics in the sense that it is a non-constructive specification of what should be computed. The computation itself is performed by means of a proof procedure.

### 4.2 An abductive proof procedure for LP

In addition to having a clear and simple semantics for abduction, it is also important to have an effective method for computing abductive explanations. Any such method will be very useful in practice in view of the many diverse applications of abductive reasoning, including default reasoning. The Theorist framework of [15, 150] provides such an implementation of abduction by means of a resolution based proof procedure.

In their study of NAF through abduction Eshghi and Kowalski [54] have defined an abductive proof procedure for NAF in logic programming. We will describe this procedure in some detail as it also serves as the basis for computing abductive explanations more generally within logic programming with other abductibles and integrity constraints (see section 5). In this section we will refer to the version of the abductive proof procedure presented in [30].

The abductive proof procedure interlaces two types of computation. The first type, referred to as the **abductive phase**, is standard SLD-resolution, which generates (negative) hypotheses and adds them to the set of abductibles being generated, while the second type, referred to as the **consistency phase**, incrementally checks that the hypotheses satisfy the integrity constraints $\mathcal{I}$ for NAF. Integrity checking of a hypothesis $p(t)$ reasons forward one step using a denial integrity constraint to derive the new denial $\lnot p(t)$, which is then interpreted as the goal $\leftarrow p(t)$. Thereafter it reasons backward in SLD-fashion in all possible ways. Integrity checking succeeds if all the branches of the resulting search space fail finitely; in other words, if the contrary of $p(t)$, namely $\lnot p(t)$, finitely fails to hold. Whenever the potential failure of a branch of the consistency phase search space is due to the failure of a selected abducible, say $q^*(s)$, a new abductive phase of SLD-resolution is triggered for the goal $\leftarrow q(s)$, to ensure that the disjunctive integrity constraint $q^*(s) \lor q(s)$ is not violated by the failure of both $q^*(s)$ and $q(s)$. This attempt to show $q(s)$ can require in turn the addition of further abductive assumptions to the set of hypotheses which is being generated.

---

5 As noticed by Dung [39], the procedure presented in [54] contains a mistake, which is not present, however, in the earlier unpublished version of the paper.

10 We use the term "consistency phase" for historical reasons. However, in view of the precise definition of integrity constraint satisfaction, some other term might be more appropriate.
branches end in a black box (indicating that some subgoal cannot be solved). A consistency phase fails if and only if one of its branches ends in a white box (indicating that integrity has been violated). It succeeds finitely if and only if all branches end in a black box (indicating that integrity has not been violated).

It is instructive to compare the computation space of the abductive proof procedure with that of SLDNF. It is easy to see that these are closely related. In particular, in both cases negative atoms need to be variable-free before they are selected. On the other hand, the two proof procedures have some important differences. A successful derivation of the abductive proof procedure will produce, together with the usual answer obtained from SLDNF, additional information, namely the abductive explanation \( \Delta \). This additional information can be useful in different ways, in particular to avoid recomputation of negative subgoals. More importantly, as the next example will show, this information will allow the procedure to handle non-stratified programs and queries for which SLDNF is incomplete. In this way the abductive proof procedure generalises SLDNF. Furthermore, the abductive explanation \( \Delta \) produced by the procedure can be recorded and used in any subsequent revision of the beliefs held by the program, in a similar fashion to truth maintenance systems [9].

To see how the abductive proof procedure extends SLDNF, consider the following program.

**Example 4.3**

\[
\begin{align*}
s & \Leftarrow q \\
s & \Leftarrow p \\
p & \Leftarrow \neg q \\
q & \Leftarrow \neg p
\end{align*}
\]

The last two clauses in this program give rise to a two-step loop via NAF, in the sense that \( p \) (and, similarly, \( q \)) “depends” negatively on itself through two applications of NAF. This causes the SLDNF proof procedure, executing the query \( \leftarrow s \), to go into an infinite loop. Therefore, the query has no SLDNF refutation. However, in the corresponding abductive framework the query has two answers, \( \Delta = \{ p^* \} \) and \( \Delta = \{ q^* \} \), corresponding to the two stable models of the program. The computation for the first answer is shown in figure 2. The outer abductive phase generates the hypothesis \( p^* \) and triggers the consistency phase for \( p^* \) shown in the double box. In general, whenever a hypothesis is tested for integrity, we can add the hypothesis to \( \Delta \) either at the beginning or at the end of the consistency phase. When this addition is done at the beginning (as originally defined in [54]) this extra information can be used in any subordinate abductive phase. In this example, the hypothesis \( p^* \) is used in the subordinate abductive proof of \( q \) to justify the failure of \( q^* \) and consequently to render \( p^* \) acceptable. In other words, the acceptability of \( p^* \) as a hypothesis is proved under the assumption of \( p^* \). The same abductive proof procedure, but where each new hypothesis is added to \( \Delta \) only at the successful completion of its consistency phase, provides a sound proof procedure for the well-founded semantics [187].

**Example 4.4**

Consider the query \( \leftarrow p \) with respect to the abductive framework corresponding to the following program.

\[
\begin{align*}
r & \Leftarrow \neg r \\
r & \Leftarrow q \\
p & \Leftarrow \neg q \\
q & \Leftarrow \neg p
\end{align*}
\]

Note that the first clause of this program give rise to a one-step loop via NAF, in the sense that \( r \) “depends” negatively on itself through one application of NAF. The abductive proof procedure succeeds with the explanation \( \{ q^* \} \), but the only set of hypotheses which satisfies the integrity constraints is \( \{ p^* \} \).

So, as Eshghi and Kowalski [54] show by means of this example, the abductive proof procedure is not always sound with respect to the above abductive semantics of NAF. In fact, following the result in [99], it can be proved that the proof procedure is sound for the class of order-consistent logic programs defined by Sato [168]. Intuitively, this is the class of programs which do not contain clauses giving rise to odd-step loops via NAF.

For the overall class of general logic programs, moreover, it is possible to argue that it is the semantics and not the proof procedure that is at fault. Indeed, Saccà and Zaniolo [164], Przymusinski [153] and others have argued that the totality requirement of stable
models is too strong. They relax this requirement and consider partial or three-valued stable models instead. In the context of the abductive semantics of NAF this is an argument against the disjunctive integrity constraints.

An abductive semantics of NAF without disjunctive integrity constraints has been proposed by Dung [39] (see section 4.3 below). The abductive proof procedure is sound with respect to this improved semantics.

An alternative abductive semantics of NAF without disjunctive integrity constraints has been proposed by Brewka [14], following ideas presented in [101]. He suggests that the set which includes both accepted and refuted NAF hypotheses be maximised. For each such set of hypotheses, the logic program admits a “model” which is the union of the sets of accepted hypotheses together with the “complement” of the refuted hypotheses. For example 1.4 the only “model” is \{p’, g, r\}. Therefore, the abductive proof procedure is still unsound with respect to this semantics. Moreover, this semantics has other undesirable consequences. For example, the program

\[ p \leftarrow p, \sim q \]

admits both \{\sim q\} and \{\sim p\} as “models”, while the only intuitively correct “model” is \{\sim q\}.

An alternative three-valued semantics for NAF has been proposed by Giordano, Martelli and Sapino [72]. According to their semantics, given the program

\[ p \leftarrow p \]

\(p\) and \(p'\) are both undefined. In contrast, \(p'\) holds in the semantics of [39], as well as in the stable model [68] and well-founded semantics [187]. Giordano, Martelli and Sapino [72] modify the abductive proof procedure so that the modification is sound and complete with respect to their semantics.

Satoh and Iwamasa [171], on the other hand, show how to extend the abductive proof procedure of [51] to deal correctly with the stable model semantics. Their extension modifies the integrity checking method of [165] and deals more generally with arbitrary integrity constraints expressed in the form of denials.

Casamayor and Decker [20] also develop an abductive proof procedure for NAF. Their proposal combines features of the Eshghi-Kowalski procedure with ancestor resolution.

Finally, we note that, to show that \(\sim p\) holds for programs such as \(p \leftarrow p\), it is possible to define a non-effective extension of the proof procedure, that allows infinite failure in the consistency phases.

### 4.3 An argumentation-theoretic interpretation

Dung [39] replaces the disjunctive integrity constraints by a weaker requirement similar to the requirement that that the set of negative hypotheses \(\Delta\) be a maximally consistent set. Unfortunately, simply replacing the disjunctive integrity constraints by maximality does not work, as shown in the following example.

**Example 4.5**

With this change the program

\[ p \leftarrow \sim q \]

has two maximally consistent extensions \(\Delta_1 = \{p'\}\) and \(\Delta_2 = \{q'\}\). However, only the second extension is computed both by SLDNF and by the abductive proof procedure. Moreover, for the same reason as in the case of the propositional Yale shooting problem discussed before, only the second extension is intuitively correct.

To avoid such problems Dung’s notion of maximality is a more subtle. He associates with every logic program \(P\) an abductive framework \((P^*, A^*, I^*)\) where \(P^*\) contains only denials

\[ \forall X . \neg p(X) \land p' (X) \]

as integrity constraints. Then, given sets \(\Delta, E\) of (negative) hypotheses, i.e. \(\Delta \subseteq A^*\), and \(E \subseteq A^*\), \(E\) can be said to attack \(\Delta\) (relative to \((P^*, A^*, I^*)\)) if \(P^* \cup E \vdash p\) for some \(p' \in \Delta\). Dung calls an extension \(P^* \cup \Delta\) of \(P^*\) preferred if

- \(P^* \cup \Delta\) is consistent with \(P^*\) and
- \(\Delta\) is maximal with respect to the property that for every attack \(E\) against \(\Delta\), \(\Delta\) attacks \(E\) (i.e. \(\Delta\) “counterattacks” \(E\) or “defends” itself against \(E\)).

Thus a preferred extension can be thought of as a maximally consistent set of hypotheses that contains its own defence against all attacks. In [39] a consistent set of hypotheses \(\Delta\) (not necessarily maximal) satisfying the property of containing its own defence against all attacks is said to be admissible (to \(P^*\)). In fact, Dung’s definition is not formulated explicitly in terms of the notions of attack and defence, but is equivalent to the one just presented.

Preferred extensions solve the problem with disjunctive integrity constraints in example 4.4 and with maximal consistency semantics in example 4.5. In example 4.4 the preferred extension semantics sanctions the derivation of \(p\) by means of an abductive derivation with generated hypotheses \(\{q'\}\). In fact, Dung proves that the abductive proof procedure is sound with respect to the preferred extension semantics. In example 4.5 the definition of preferred extension excludes the maximally consistent extension \(\{p'\}\), because there is no defence against the attack \(q'\).

The preferred extension semantics provides a unifying framework for various approaches to the semantics of negation in LP. Kakas and Mancarella [69] show that it is equivalent to Sacca and Zanolo’s partial stable model semantics [164]. Like the partial stable model semantics, it includes the stable model semantics as a special case.

Dung [39] also defines the notion of complete extension. An extension \(P^* \cup \Delta\) is complete if

\[ ^{11}\text{Alternatively, instead of the symbol } \sim \text{ we could use the symbol } \neg , \text{ here and elsewhere in the paper where we define the notion of "attack".} \]
\[ \Delta = \{ p^* \} \text{ for each attack } E \text{ against } \{ p^* \}, \Delta \text{ attacks } E \]

(i.e. \( \Delta \) is admissible and it contains all hypotheses it can defend against all attacks).

Stationary expansions [154] are equivalent to complete extensions, as shown in [16]. Moreover, Dung shows that the **well-founded model** [187] is the smallest complete extension that can be constructed bottom-up from the empty set of negative hypotheses, by adding incrementally all admissible hypotheses. Thus the well-founded semantics is minimalistic and sceptical, whereas the preferred extension semantics is maximalist and credulous. The relationship between these two semantics is further investigated in [17], where the well-founded model and preferred extensions are shown to correspond to the least fixed point and greatest fixed point, respectively, of the same operator.

Kalas and Mancarella [96, 97] propose an improvement of the preferred extension semantics. Their proposal can be illustrated by the following example.

**Example 4.6**

Consider the program

\[
\begin{align*}
p & \leftarrow \sim q \\
q & \leftarrow \sim q.
\end{align*}
\]

Similarly to example 4.4, the last clause gives rise to a one-step loop via NAF, since \( q \) “depends” negatively on itself through one application of NAF. In the correlative framework corresponding to this program consider the set of hypotheses \( \Delta = \{ p \} \). The only attack against \( \Delta \) is \( E = \{ q \} \), and the only attack against \( E \) is \( E \) itself. Thus \( \Delta \) is not an admissible extension of the program according to the preferred extension semantics, because \( \Delta \) cannot defend itself against \( E \). The empty set is the only preferred extension. However, intuitively \( \Delta \) should be admissible because the only attack against \( \Delta \) attacks itself, and therefore should not be regarded as an admissible attack against \( \Delta \).

To deal with this kind of example, Kalas and Mancarella [96, 97] modify Dung’s semantics, increasing the number of ways in which an attack \( E \) can be defeated. Whereas Dung only allows \( \Delta \) to defeat an attack \( E \), they also allow \( E \) to defeat itself. They call a set of hypotheses \( \Delta \) **weakly stable** if

- for every attack \( E \) against \( \Delta \), \( E \cup \Delta \) attacks \( E - \Delta \).

Moreover, they call an extension \( P^* \cup \Delta \) of \( P^* \) a **stable theory** if \( \Delta \) is maximally weakly stable. Note that here the condition “\( P^* \cup \Delta \) is consistent with \( P^* \)” of the definition of preferred extensions and admissible sets of hypotheses is subsumed by the new condition. This is a consequence of another difference between [96, 97] and [39], namely that for each attack \( E \) against \( \Delta \) the counter-attack is required to be against \( E - \Delta \) rather than against \( E \). In other words, the defence of \( \Delta \) must be a genuine attack that does not at the same time also attack \( \Delta \). Therefore, if \( \Delta \) is inconsistent, it contains as a subset an attack \( E \), which can not be counterattacked because \( E - \Delta \) is empty. In [97], Kalas and Mancarella show how these notions can also be used to extend the sceptical well-founded model semantics. In example 4.6 above this extension of the well-founded model will contain the negation of \( p \).

Like the original definition of admissible sets of hypotheses and preferred extension, the definition of weakly stable sets of hypotheses and stable theories was not originally formulated in terms of attack, but is equivalent to the one presented here.

Kalas and Mancarella [97] argue that the notion of defeating an attack needs to be liberalised further. They illustrate their argument with the following example.

**Example 4.7**

Consider the program \( P \)

\[
\begin{align*}
s & \leftarrow \sim p \\
p & \leftarrow \sim q \\
q & \leftarrow \sim r \\
r & \leftarrow \sim p.
\end{align*}
\]

The last three clauses give rise to a three-step loop via NAF, since \( p \) (and, similarly, \( q \) and \( r \)) “depends” negatively on itself through three application of NAF. In the corresponding abductive framework, the only attack against the hypothesis \( s^* \) is \( E = \{ p^* \} \). But although \( P^* \cup \{ s^* \} \cup E \) does not attack \( E \), \( E \) is not a valid attack because it is not stable (or admissible) according to the definition above.

To generalise the reasoning in this example so that it gives an intuitively correct semantics to any program with clauses giving rise to an odd-step loop via NAF, we need to liberalise further the conditions for defeating \( E \). Kalas and Mancarella suggest a recursive definition in which a set of hypotheses is deemed acceptable if no attack against it is acceptable.

More precisely, given an initial set of hypotheses \( \Delta_0 \), a set of hypotheses \( \Delta \) is **acceptable** to \( \Delta_0 \) if

for every attack \( E \) against \( \Delta - \Delta_0 \), \( E \) is not acceptable to \( \Delta \cup \Delta_0 \).

The semantics of a program \( P \) can be identified with any \( \Delta \) which is maximally acceptable to the empty set of hypotheses \( \emptyset \). As before with weak stability and stable theories, the consideration of attacks only against \( \Delta - \Delta_0 \) ensures that attacks and counterattacks are genuine, i.e. they attack the new part of \( \Delta \) that does not contain \( \Delta_0 \).

Notice that, as a special case, we obtain a basis for the definition:

\[ \Delta \text{ is acceptable to } \Delta_0 \text{ if } \Delta \subseteq \Delta_0. \]

Therefore, if \( \Delta \) is acceptable to \( \emptyset \) then \( \Delta \) is consistent.

Notice, too, that applying the recursive definition twice, and starting with the base case, we obtain an approximation to the recursive definition

\[ \Delta \text{ is acceptable to } \Delta_0 \text{ if for every attack } E \text{ against } \Delta - \Delta_0 \]

\[ E \cup \Delta \cup \Delta_0 \text{ attacks } E \cup (\Delta \cup \Delta_0). \]

Thus, the stable theories are those which are maximally acceptable to \( \emptyset \) where acceptability is defined by this approximation to the recursive definition.
A related argumentation-theoretic interpretation for the semantics of NAF in LP has also been developed by Geffner [67]. This interpretation is equivalent to the well-founded semantics [13]. Based upon Geffner’s notion of argumentation, Torres [185] has proposed an argumentation-theoretic semantics for NAF that is equivalent to Kakas and Mancarella’s stable theory semantics [90, 91], but is formulated in terms of the following notion of attack: $E$ attacks $\Delta$ (relative to $P^r$) if $P^r \cup E \cup \Delta \vdash p$ for some $p^r \in \Delta$.

Alferes and Pereira [41] apply the argumentation-theoretic interpretation introduced in [88] to expand the well-founded model of normal and extended logic programs (see section 5). In the case of normal logic programming, their semantics gives the same result as the acceptability semantics in example 4.7.

Simari and Loui [177] define an argumentation-theoretic framework for default reasoning in general. They combine a notion of acceptability with Poole’s notion of “most specific” explanation [143], to deal with hierarchies of defaults.

In section 7 we will present an abstract argumentation-theoretic framework which is based upon the framework for LP but unifies many other approaches to default reasoning.

### 4.4 An argumentation-theoretic interpretation of the abductive proof procedure

As mentioned above, the incorrectness (with respect to the stable model semantics) of the abductive proof procedure can be remedied by adopting the preferred extension, stable theory or acceptability semantics. This reinterpretation of the original abductive proof procedure in terms of an improved semantics, and the extension of the proof procedure to capture further improvements in the semantics, is an interesting example of the interaction that can arise between a program (proof procedure in this case) and its specification (semantics).

To illustrate the argumentation-theoretic interpretation of the proof procedure, consider again figure 1 of example 4.2. The consistency phase for $p^r$, shown in the outer-most double box, can be understood as searching for any attack against $\{p^r\}$. The only attack, namely $\{q^r\}$, is counterattacked (thereby defending $\{p^r\}$) by assuming the additional hypothesis $r^*$, as this implies $q$. Hence the set $\Delta = \{p^r, r^*\}$ is admissible, i.e., it can defend itself against any attack, since all attacks against $\{p^r\}$ are counterattacked by $r^*$ and there are no attacks against $r^*$.

In general, the proof procedure constructs an admissible set of negative hypotheses in two steps. First, it constructs a set of hypotheses which is sufficient to solve the original goal. Then, it augments this set with the hypotheses necessary to defend the first set against attack.

The argumentation-theoretic interpretation suggests how to extend the proof procedure to capture more fully the stable theory semantics and more generally the semantics given by the recursive definition for acceptability. The extension, presented in [182], involves temporarily remembering a (selected) attack $E$ and using $E$ itself together with the subset of $\Delta$ generated so far, to counterattack $E$, in the subordinate abductive phase.

For example 4.6 of section 4.3, as shown in figure 3, to defend against the attack $q^r$ on $p^r$, we need to temporarily remember $q^r$ and use it in the subordinate abductive phase to prove $q$ and therefore to attack $q^r$ itself.

In the original abductive proof procedure of [54], hypotheses in defences are always added to $\Delta$. However, in the proof procedure for the acceptability semantics, defences $D$ can not always be added to $\Delta$, because even though $D$ might be acceptable to $\Delta$, $\Delta \cup D$ might not be acceptable to $\emptyset$. This situation arises for the three step loop program of example 4.7, where $D = \{q^r\}$ is used to defend $\Delta = \{s^r\}$ against the attack $E = \{p^r\}$, but $\Delta \cup D$ is not acceptable to $\emptyset$.

To cater for this characteristic of the acceptability semantics, the extended proof procedure non-deterministically considers two cases. For each hypothesis in a defence $D$ against an attack $E$ against $\Delta$, the hypothesis either can be added to $\Delta$ or can be remembered temporarily to counterattack any attack $E'$ against $D$, together with $\Delta$ and $E$. In general, a sequence of consecutive attacks and defences $E, D, E', D', \ldots$ can be generated before an acceptable abductive explanation $\Delta$ is found, and the same non-deterministic consideration of cases is applied to $D'$ and all successive defences in the sequence.

The definitions of admissible, stable and acceptable sets $\Delta$ of hypotheses all require that every attack against $\Delta$ be counterattacked. Although every superset of an attack is also an attack, the abductive proof procedure in [54] only considers those “minimal” attacks.
generated by SLD, without examining superset attacks. This is possible because all supersets of an attack can be counterattacked in exactly the same way as the attack itself, which is generated by SLD. For this reason, the proof procedure of [54] is sound for the admissibility semantics. Unfortunately, supersets of attacks need to be considered to guarantee soundness of the proof procedure for the acceptability semantics. In [182], however, Toni and Kakas prove that only certain supersets of “minimally generated” attacks need to be considered.

The additional features required for the proof procedure to capture more fully the acceptability semantics render the proof procedure considerably more complex and less efficient than proof procedures for simpler semantics. However, this extra complexity is due to the treatment of any odd-step loops via NAF and such programs seem to occur very rarely in practice. Therefore, in most cases it is sufficient to consider the approximation of the proof procedure which computes the preferred extension and stable theory semantics. This approximation improves upon the Eshghi-Kowalski proof procedure, since in the case of finite failure it terminates earlier, avoiding unnecessary computation.

5 Abductive Logic Programming

Abductive Logic Programming (ALP), as understood in the remainder of this paper, is the extension of LP to support abduction in general, and not only the use of abduction for NAF. This extension was introduced already in section 1, as the special case of an abductive framework \( \langle T, A, I \rangle \), where \( T \) is a logic program. In this paper we will assume, without loss of generality, that abducible predicates do not have definitions in \( T \), i.e. do not appear in the heads of clauses in the program \( T \). This assumption has the advantage that all explanations are thereby guaranteed to be basic.

Semantics and proof procedures for ALP have been proposed by Eshghi and Kowalski [33], Kakas and Mancarella [90] and Chen and Warren [23]. Chen and Warren extend the perfect model semantics of Przymusinski [152] to include abducibles and integrity constraints over abducibles. Here we shall concentrate on the proposal of Kakas and Mancarella, which extends the stable model semantics.

5.1 Generalised stable model semantics

Kakas and Mancarella [90] develop a semantics for ALP by generalising the stable model semantics for LP. Let \( \langle P, A, I \rangle \) be an abductive framework, where \( P \) is a general logic program, and let \( \Delta \) be a subset of \( A \). \( M(\Delta) \) is a generalised stable model of \( \langle P, A, I \rangle \), if

- \( M(\Delta) \) is a stable model of \( P \cup \Delta \), and
- \( M(\Delta) \models I \).

Here the semantics of the integrity constraints \( I \) is defined by the second condition in the definition above. Consequently, an abductive extension \( P \cup \Delta \) of the program \( P \) satisfies \( I \) if and only if there exists a stable model \( M(\Delta) \) of \( P \cup \Delta \) such that \( I \) is true in \( M(\Delta) \).

Note that in a similar manner, it is possible to generalise other model-theoretic semantics for logic programs, by considering only those models of \( P \cup \Delta \) (of the appropriate kind, e.g. partial stable models, well-founded models etc.) in which the integrity constraints are all true.

Generalised stable models are defined independently from any query. However, given a query \( Q \), we can define an abductive explanation for \( Q \) in \( \langle P, A, I \rangle \) to be any subset \( \Delta \) of \( A \) such that

- \( M(\Delta) \) is a generalised stable model of \( \langle P, A, I \rangle \), and
- \( M(\Delta) \models Q \).

Example 5.1

Consider the program \( P \):

\[
p \leftarrow a,
q \leftarrow b,
\]

with \( A = \{a, b\} \) and integrity constraint \( I \):

\[
p \leftarrow q.
\]

The interpretations \( M(\Delta_1) = \{a, p\} \) and \( M(\Delta_2) = \{a, k, p, q\} \) are generalised stable models of \( \langle P, A, I \rangle \). Consequently, both \( \Delta_1 = \{a\} \) and \( \Delta_2 = \{a, k\} \) are abductive explanations of \( p \). On the other hand, the interpretation \( \{k, q\} \), corresponding to the set of abducibles \( \{k\} \), is not a generalised stable model of \( \langle P, A, I \rangle \), because it is not a model of \( I \) as it does not contain \( p \). Moreover, the interpretation \( \{k, q, p\} \), although it is a model of \( P \cup I \) and therefore satisfies \( I \) according to the consistency view of constraint satisfaction, is not a generalised stable model of \( \langle P, A, I \rangle \), because it is not a stable model of \( P \). This shows that the notion of integrity satisfaction for ALP is stronger than the consistency view. It is also possible to show that it is weaker than the theoremhood view, and to argue that it is similar to the metalevel or epistemic view.

An alternative, and perhaps more fundamental way of understanding the generalised stable model semantics is by using abduction both for hypothetical reasoning and for NAF. The negative literals in \( \langle P, A, I \rangle \) can be viewed as further abducibles according to the transformation described in section 1. The set of abducible predicates then becomes \( A \cup A^* \), where \( A^* \) is the set of negative abducibles introduced by the transformation. This results in a new abductive framework \( \langle P^*, A \cup A^*, I \cup P \rangle \), where \( P^* \) is the set of special...
integrity constraints introduced by the transformation of section 4. The semantics of the abductive framework \((P', A \cup A', I \cup I')\) can then be given by the sets \(\Delta_\star\) of hypotheses drawn from \(A \cup A'\) which satisfy the integrity constraints \(I \cup I'\).

**Example 5.2**

Consider \(P\)

\[
p \leftarrow a, \sim q \\
q \leftarrow b
\]

with \(A = \{a, b\}\) and \(I = \emptyset\). If \(Q = \sim p\) then \(\Delta_\star = \{a, q', b\}\) is an explanation for \(Q' = Q\) in \((P', A \cup A', I \cup I')\). Note that \(b\) is in \(\Delta_\star\) because \(I'\) contains the disjunctive integrity constraint \(b \lor b'\).

Kalisz and Mancarella show one to one correspondence between the generalised stable models of \((P, A, I)\) and the sets of hypotheses \(\Delta_\star\) that satisfy the transformed framework \((P', A \cup A', I \cup I')\). Moreover they show that for any abductive explanation \(\Delta_\star\) for a query \(Q\) in \((P', A \cup A', I \cup I')\), \(\Delta = \Delta_\star \cap A\) is an abductive explanation for \(Q\) in \((P, A, I)\).

**Example 5.3**

Consider the framework \((P, A, I)\) and the query \(Q\) of example 5.2. We have already seen that \(\Delta_\star = \{a, q', b\}\) is an explanation for \(Q' = Q\) in \((P', A \cup A', I \cup I')\). Accordingly the subset \(\Delta = \{a\}\) is an explanation for \(Q\) in \((P, A, I)\).

Note that the generalised stable model semantics as defined above requires that for each abducible \(a\), either \(a\) or \(a'\) holds. This can be relaxed by dropping the disjunctive integrity constraints \(a \lor a'\) and defining the set of abducible hypotheses \(A\) to include both \(a\) and \(a'\). Such a relaxation would be in the spirit of replacing stable model semantics by admissible or preferred extensions in the case of ordinary LP.

Generalised stable models combine the use of abduction for default reasoning (in the form of NAF) with the use of abduction for other forms of hypothetical reasoning. In the generalised stable model semantics, abduction for default reasoning is expressed solely by NAF. However, in the event calculus persistence axiom presented in section 2 the predicate \(\text{persists}\) is a positive abducible that has a default nature. Therefore, instances of \(\text{persists}\) should be abduced unless some integrity constraint is violated. Indeed, in standard formulations of the persistence axiom the positive atom \(\text{persists}(T_1, T_2)\) is replaced by a negative literal \(\sim \text{clipped}(T_1, T_2)\) [176, 35]. In contrast, the abduction of \(\text{happens}\) is used for non-default hypothetical reasoning. The distinction between default reasoning and non-default abduction is also made in Konolige's proposal [103], which combines abduction for non-default hypothetical reasoning with default logic [158] for default reasoning. This proposal is similar, therefore, to the way in which generalised stable models combine abduction with NAF. Poole [147], on the other hand, proposes an abductive framework where abducibles can be specified either as default, like \(\text{persists}\), or non-default, like \(\text{happens}\). In [183], Toni and Kowalski show how both default and non-default abducibles can be reduced to NAF. This reduction is discussed in section 5.5 below.

The knowledge representation problem in ALP is complicated by the need to decide whether information should be represented as part of the program, as an integrity constraint, or as an observation to be explained, as illustrated by the following example taken from [9].

**Example 5.4**

\[
\text{fly}(X) \leftarrow \text{bird}(X), \sim \text{abnormal} \text{bird}(X) \\
\text{abnormal} \text{bird}(X) \leftarrow \text{penguin}(X) \\
\text{has}_\text{beak}(X) \leftarrow \text{bird}(X).
\]

Suppose that \(\text{bird}\) is abducible and consider the three cases in which \(\text{fly}(\text{tweety})\)

is either added to the program, added to the integrity constraints, or considered as the observation to be explained. In the first case, the abducible \(\text{bird}(\text{tweety})\) and, as a consequence, the atom \(\text{has}_\text{beak}(\text{tweety})\) belong to some, but not all, generalised stable models. Instead, in the second case every generalised stable model contains \(\text{bird}(\text{tweety})\) and \(\text{has}_\text{beak}(\text{tweety})\). In the last case, the observation is assimilated by adding the explanation \(\{\text{bird}(\text{tweety})\}\) to the program, and therefore \(\text{has}_\text{beak}(\text{tweety})\) is derived in the resulting generalised stable model. Thus, the last two alternatives have similar effects. Dencker and DeSchreye [33] argue that the second alternative is especially appropriate for knowledge representation in the temporal reasoning domain.

### 5.2 An abductive proof procedure for ALP

In [91, 92, 93], a proof procedure is given to compute abductive explanations in ALP. This extends the abductive proof procedure for NAF [54] described in section 4.2, retaining the basic structure which interleaves an abductive phase that generates and collects abductive hypotheses with a consistency phase that incrementally checks these hypotheses for integrity. We will illustrate these extended proof procedure by means of examples.

**Example 5.5**

Consider again example 4.2. The abductive proof procedure for NAF fails on the query \(\leftarrow p\). Ignoring, for the moment, the construction of the set \(\Delta\), the computation is that shown inside the outer double box of figure 1 with the abductive and consistency phases interchanged, i.e. the type of each box changed from a double box to a single box and vice-versa. Suppose now that we have the same program and query but in an ALP setting where the predicate \(r\) is abducible. The query will then succeed with the explanation \(\Delta = \{q', r\}\) as shown in figure 4. As before the computation arrives at a point where \(r\) needs to be proved. Whereas this failed before, this succeeds now by abducing \(r\). Hence by adding the hypothesis \(r\) to the explanation we can ensure that \(q'\) is acceptable.
An important feature of the abductive proof procedures is that they avoid performing a full general-purpose integrity check (such as the forward reasoning procedure of [111]). In the case of a negative hypothesis, $q^*$ for example, a general-purpose forward reasoning integrity check would have to use rules in the program such as $p \leftarrow q^*$ to derive $p$. The optimised integrity check in the abductive proof procedure avoids this inference and only reasons forward one step with the integrity constraint $\neg(q \land \neg q^*)$, deriving the resolvent $\neg q$, and then reasoning backward from the resolvent.

Similarly, the integrity check for a positive hypothesis, $r$ for example, avoids reasoning forward with any rules which might have $r$ in the body. Indeed, in a case, such as example 5.5 above, where there are no domain specific integrity constraints, the integrity check for a positive abducible, such as $r$, simply consists in checking that its complement, in our example $r^*$, does not belong to $\Delta$.

To ensure that this optimised form of integrity check is correct, the proof procedure is extended to record those positive abducibles it needs to assume absent to show the integrity of other abducibles in $\Delta$. So whenever a positive abducible, which is not in $\Delta$, is selected in a branch of a consistency phase, the procedure fails on that branch and at the same time records that this abducible needs to be absent. This extension is illustrated by the following example.

**Example 5.6**

Consider the program

\[
\begin{align*}
p & \leftarrow \neg q, r \\
q & \leftarrow r
\end{align*}
\]

where $r$ is a abducible and the query is $\leftarrow p$ (see figure 5). The acceptability of $q^*$ requires the absence of the abducible $r$. The simplest way to ensure this is by adding $r^*$ to $\Delta$. This, then, prevents the abduction of $r$ and the computation fails. Notice that the proof procedure does not reason forward from $r$ to test its integrity. This test has been performed backwards in the earlier consistency phase for $q^*$, and the addition of $r^*$ to $\Delta$ ensures that it is not necessary to repeat it.

The way in which the absence of abducibles is recorded depends on how the negation of each abducible is interpreted. Under the stable and generalised stable model semantics, as we have assumed in example 5.6 above, the required failure of a positive abducible is recorded by adding its complement to $\Delta$. However, in general it is not always appropriate to assume that the absence of an abducible implies its negation. On the contrary, it may be appropriate to treat abducibles as open rather than closed (see section 6.1), and correspondingly to treat the negation of abducible predicates as open. As we shall argue later, this might be done by treating such a negation as a form of explicit negation, which is also abducible. In this case recording the absence of a positive abducible by adding its complement to $\Delta$ is too strong, and we will use a separate (purely computational) data structure to hold this information.

Integrity checking can also be optimised when there are domain specific integrity constraints provided the constraints can be formulated as denials containing at least one literal whose predicate is abducible. In this case the abductive proof procedure needs

\[
p \leftarrow q = \neg[q \land \neg r],
\]

\footnote{Notice that any integrity constraint can be transformed into a denial (possibly with the introduction of new auxiliary predicates). For example:}
Nevertheless the proof procedure is sound because the violation is found later by backward reasoning when a is resolved with the second integrity constraint.

In summary, the overall effect of additional integrity constraints is to increase the size of the search space during the consistency phase, with no significant change to the basic structure of the backward reasoning procedure.

Even if the absence of abducibles is not identified with the presence of their complement, the abductive proof procedure \cite{91, 92, 93} described above suffers from the same soundness problem shown in section 4 for the abductive proof procedure for NAF. This problem can be solved similarly, by replacing stable models with any of the non-total semantics for NAF mentioned in section 4 (partial stable models, preferred extensions, stable theories or acceptability semantics). Replacing the stable models semantics by any of these semantics requires that the notion of integrity satisfaction be revised appropriately. This is an interesting problem for future work.

The soundness problem can also be addressed by providing an argumentation-theoretic semantics for ALP which treats integrity constraints and NAF uniformly via an appropriately extended notion of attack. In section 5.3 we will see that this alternative approach arises naturally from an argumentation-theoretic reinterpretation of the abductive proof procedure for ALP.

The proof procedure can be also modified to provide a sound computational mechanism for the generalised stable model semantics. This approach has been followed by Satoh and Iwawama \cite{170}, as we illustrate in section 5.4.

### 5.3 An argumentation-theoretic interpretation of the abductive proof procedure for ALP

Similarly to the LP case, the abductive proof procedure for ALP can be reinterpreted in argumentation-theoretic terms. For the ALP procedure, attacks can be provided as follows:

- via NAF:
  
  Relative to $\langle P^*, A \cup A', I \cup I^* \rangle$, $E$ attacks $\Delta$ via NAF if
  \[
  E \text{ attacks } \Delta \text{ as in section 4.3, i.e. } P^* \cup E \vdash p \text{ for some } p^* \in \Delta, \text{ or } a^* \in E, \text{ for some abducible } a \in \Delta;
  \]

- via integrity constraints

  Relative to $\langle P^*, A \cup A', I \cup I^* \rangle$, $E$ attacks $\Delta$ via an integrity constraint
  \[
  \neg (L_1 \land \ldots \land L_n) \text{ in } I \text{ if } P^* \cup E \vdash L_1, \ldots, L_{i-1}, L_{i+1}, \ldots, L_n, \text{ for some } L_i \in \Delta. \tag{16}
  \]

To illustrate the argumentation-theoretic interpretation of the proof procedure for ALP, consider again figure 6 of example 5.7. The consistency phase for a, shown in the outer double box, can be understood as searching for attacks against $[a]$. There are two such attacks:

$$p \lor q = \neg \neg p \land \neg q$$

\footnote{Recall that the abductive proof procedure for ALP employs the restriction that each integrity constraint contains at least one literal with an abducible predicate.}
attacks. \{q^*\} and \{b\}, shown by the two branches in the figure. \{q^*\} attacks \{a\} via the integrity constraint \(\neg (a \land p)\) in \(I\), since \(q^*\) implies \(p\). Analogously, \{b\} attacks \{a\} via the integrity constraint \(\neg (a \land q)\) in \(I\), since \(b\) implies \(q\). The first attack \(\{q^*\}\) is counterattacked by \{b\}, via NAF (as in section 4.3), since this implies \(q\). This is shown in the single box. The hypothesis \(b\) is added to \(\Delta\) since the attack \{b\} against \{b\}, via NAF, is trivially counterattacked by \{b\}, via NAF, as sketched in the inner double box. However, \{b\} attacks \{a\}, as shown by the right branch in the outer double box. Therefore, \(\Delta\) attacks itself, and this causes failure of the proof procedure.

The analysis of the proof procedure in terms of attacks and counterattacks suggests the following argumentation-theoretic semantics for ALP. A set of hypotheses \(\Delta\) is KM-admissible if

- for every attack \(E\) against \(\Delta\),
  \(\Delta\) attacks \((E = \Delta)\) via NAF alone.

In section 6.5 we will see that the notion of KM-admissible set of hypotheses is similar to the notion of admissibility proposed by Dung [45] for extended logic programming, in that only attacks via NAF are allowed to counterattack.

The argumentation-theoretic interpretation of ALP suggests several ways in which the semantics and proof procedure for ALP can be modified. Firstly, the notion of attack itself can be modified, e.g. following Torre’s equivalent formulation of the stable theory semantics [185] (see section 4.3). Secondly, the notion of admissibility can be changed to allow counterattacks via integrity constraints, as well as via NAF. Finally, as in the case of standard LP, the notion of admissibility can be replaced by other semantic notions such as weak stability and acceptability (see section 4.3). The proof procedure for ALP can be modified appropriately to reflect each of these modifications. Such modifications of the semantics and the corresponding modifications of the proof procedure require further investigation.

Using the definition of well-founded semantics given in section 4.3, (non-default) abducibles are always undefined, and consequently fulfill no function, in the well-founded semantics of ALP, as illustrated by the following example.

**Example 5.8**
Consider the propositional abductive framework \((P; A; I)\) where \(P\) is
\[
\begin{align*}
p & \leftarrow a \\
r & \leftarrow \neg q \\
q & \leftarrow r \\
\end{align*}
\]
\(A = \{a\}\), and \(I = \emptyset\). The well-founded model of \((P; A; I)\) is \(\emptyset\).

In [136], Pereira, Aparicio and Alferes define an alternative, generalised well-founded semantics for ALP where first programs are extended by a set of abducibles as in the case of generalised stable models, and then the well-founded semantics (rather than stable model semantics) is applied to the extended programs. As a result, the well-founded models of an abductive framework are not unique. In the example above, \(\emptyset, \{p^*; a^*\}\) and \(\{p; a\}\) are the generalised well-founded models of \((P; A; I)\). Note that in this application of the well-founded semantics, if an abducible is not in a set of hypotheses \(\Delta\) then its negation does not necessarily belong to \(\Delta\). Thus the negation of an abducible is not interpreted as NAF. Moreover, since abducible predicates can be undefined some of the non-abducible predicates can also be undefined.

### 5.4 Computation of abduction through TMS

Satoh and Iwayama [170] present a method for computing generalised stable models for logic programs with integrity constraints represented as denials. The method is a bottom-up computation based upon the TMS procedure of [30]. Although the computation is not goal-directed, goals (or queries) can be represented as denials and be treated as integrity constraints.

Compared with other bottom-up procedures for computing generalised stable model semantics, which first generate stable models and then test the integrity constraints, the method of Satoh and Iwayama dynamically uses the integrity constraints during the process of generating the stable models, in order to prune the search space more efficiently.

**Example 5.9**
Consider the program
\[
\begin{align*}
p & \leftarrow q \\
r & \leftarrow \neg q \\
q & \leftarrow r \\
\end{align*}
\]
and the set of integrity constraints \(I = \{\neg p\}\). \(P\) has two stable models \(M_1 = \{p, q\}\) and \(M_2 = \{r\}\), but only \(M_2\) satisfies \(I\). The proof procedure of [170] deterministically computes only the intended model \(M_2\), without first computing and then rejecting \(M_1\).

In section 8 we will see more generally that truth maintenance systems can be regarded as a form of ALP.

### 5.5 Simulation of abduction

Satoh and Iwayama [170] also show that an abductive logic program can be transformed into a logic program without abducibles but where the integrity constraints remain. For each abducible predicate \(p\) in \(A\), a new predicate \(p'\) is introduced, which intuitively represents the complement of \(p\), and a new pair of clauses
\[
\begin{align*}
p(X) & \leftarrow \neg p'(X) \\
p'(X) & \leftarrow p(X)
\end{align*}
\]
is added to the program. In effect abductive assumptions of the form \(p(t)\) are thereby transformed into NAF assumptions of the form \(\neg p'(t)\). Satoh and Iwayama apply the generalised stable model semantics to the transformed program. However, the transformational semantics, which is effectively employed by Satoh and Iwayama, has the advantage that any semantics can be used for the resulting transformed program.

\[\text{Satoh and Iwayama use the notation } p^\ast \text{ instead of } p' \text{ and explicitly consider only propositional programs.}\]
Example 5.10
Consider the abductive framework \((P, A, I)\) of example 5.1. The transformation generates a new theory \(P'\) with the additional clauses
\[
\begin{align*}
a & \leftarrow \neg a' \\
a' & \leftarrow a \\
b & \leftarrow \neg b' \\
b' & \leftarrow b.
\end{align*}
\]

\(P'\) has two generalised stable models that satisfy the integrity constraints, namely \(M'_1 = M(\Delta_1) \cup \{b'\} = \{a, p, b'\}\), and \(M'_2 = M(\Delta_2) = \{a, b, p, q\}\) where \(M(\Delta_1)\) and \(M(\Delta_2)\) are the generalised stable models seen in example 3.1.

An alternative way of viewing abduction, which emphasises the defeasibility of abducibles, is retractability [70]. Instead of regarding abducibles as atoms to be consistently added to a theory, they can be considered as assertions in the theory to be retracted in the presence of contradictions until consistency (or integrity) is restored (c.f. section 6.2).

One approach to this understanding of abduction is presented in [111]. Here, Kowalski and Sadri present a transformation from a general logic program \(P\) with integrity constraints \(I\), together with some indication of how to restore consistency, to a new general logic program \(P'\) without integrity constraints. Restoration of consistency is indicated by nominating one atom as retractable in each integrity constraint \(^{18}\). Integrity constraints are represented as denials, and the atom to be retracted must occur positively in the integrity constraint. The (informally specified) semantics is that whenever an integrity constraint of the form
\[
\neg [p \land q]
\]
has been violated, where the atom \(p\) has been nominated as retractable, then consistency should be restored by retracting the instance of the clause of the form
\[
\neg p \land q
\]
which has been used to derive the inconsistency.

The transformation of \([111]\) replaces a program \(P\) with integrity constraints \(I\) by a program \(P'\) without integrity constraints which is always consistent with \(I\); and if \(P\) is inconsistent with \(I\), then \(P'\) represents one possible way to restore consistency (relative to the choice of the retractable atom).

Given an integrity constraint of the form
\[
\neg [p \land q]
\]
where \(p\) is retractable, the transformation replaces the integrity constraints and every clause of the form
\[
p \leftarrow r
\]
by
\[
p \leftarrow r \leftarrow \neg q
\]
where the condition \(\neg q\) may need to be transformed further, if necessary, into general logic form, and where the transformation needs to be repeated for every integrity constraint. Kowalski and Sadri show that if \(P\) is a stratified program with appropriately stratified integrity constraints \(I\), so that the transformed program \(P'\) is stratified, then \(P'\) computes the same consistent answers as \(P\) with \(I\).

Notice that retracting abducible hypotheses is a special case where the abducibility of a predicate \(a\) is represented by an assertion
\[
a(X),
\]
where \(X\) is a set of variables.

The following example illustrates the behaviour of the transformation when applied to ALP.

Example 5.11
Consider the simplified version of the event calculus presented in example 2.1. If the integrity constraint
\[
\neg \text{[persists}(T_1, P, T_2) \land \text{happens}(E, T) \land \text{terminates}(E, P) \land T_1 \leq T \leq T_2]
\]
is violated, then it is natural to restore integrity by retracting the instance of \(\text{persists}(T_1, P, T_2)\) that has led to the violation. Thus, \(\text{persists}(T_1, P, T_2)\) is the retractable in this integrity constraint. By applying the transformation sketched above, the integrity constraint and the use of abduction can be replaced by the clauses obtained by further transforming
\[
\text{persists}(T_1, P, T_2) \leftarrow \neg \text{[happens}(E, T), \text{terminates}(E, P), T_1 \leq T \leq T_2]
\]
into general LP form.

One problem with the retractability semantics is that the equivalence of the original program with the transformed program was proved only in the case where the resulting transformed program is locally stratified. Moreover the proof of equivalence was based on a tedious comparison of search spaces for the two programs. This problem was addressed in a subsequent paper [112] in which integrity constraints are re-expressed as extended clauses and the retractable atoms become explicitly negated conclusions. This use of extended clauses in place of integrity constraints with retractibles is discussed later in section 6.3.

The transformation of \([111]\), applied to ALP, treats all abducibles as default abducibles. In particular, abducibles which do not occur as retractibles in integrity constraints are simply asserted in the transformed program \(P'\). Therefore, this transformation can only be used to eliminate default abducibles together with their integrity constraints. A more complete transformation [83] can be obtained by combining the use of retractibles to eliminate integrity constraints with the transformation of \([70]\) for reducing non-default abducibles to NAF. The new transformation is defined for abductive frameworks where every integrity constraint has a retractible which is either an abducible or the NAF of an
As an example, consider the propositional abductive logic program \( \langle P; A; I \rangle \) where \( P \) contains the clause
\[
p \leftarrow a
\]
\( a \) is in \( A \), and \( I \) contains the integrity constraint
\[
\neg[a \land q]
\]
where \( a \) is retractible. If \( a \) is a default abducible, the transformation generates the logic program \( P' \)
\[
p \leftarrow \neg a'
\]
\( a' \leftarrow q \)
\( a \leftarrow \neg a'
\]
where, as before, \( a' \) stands for the complement of \( a \). The first clause in \( P' \) is obtained by replacing the positive condition \( a \) in the clause in \( P \) by the NAF literal \( \neg a' \). The second clause replaces the integrity constraint in \( I \). Note that this replaces “\( a \) should be retracted” if the integrity constraint \( \neg[a \land q] \) is violated by “the complement \( a' \) of \( a \) should be asserted”. Finally, the last clause in \( P' \) expresses the nature of \( a \) as a default abducible. Namely, \( a \) holds by default, unless some integrity constraint is violated. In this example, \( a \) holds if \( q \) does not hold.

If \( a \) is a non-default abducible, then the logic program \( P' \) obtained by transforming the same abductive program \( \langle P; A; I \rangle \) also contains the fourth clause
\[
a' \leftarrow a
\]
that, together with the third clause, expresses that neither \( a \) nor \( a' \) need hold, even if no integrity constraint is violated. Note that the last two clauses in \( P' \) are those used by Satoh and Iwawaya [170] to simulate non-default abduction by means of NAF.

Toni and Kowalski [183] prove that the transformation is correct and complete in the sense that there is a one-to-one correspondence between attacks in the framework \( \langle P; A; I \rangle \) and in the framework corresponding to the transformed program \( P' \). Thus, for any semantics that can be defined argumentation-theoretically there is a one-to-one correspondence between the semantics for an abductive logic program and the semantics of the transformed program. As a consequence, any proof procedure for LP which is correct for one of these semantics provides a correct proof procedure for ALP for the analogous semantics (and, less interestingly, vice versa).

In addition to the transformations from ALP to general LP, discussed above, transformations between ALP and disjunctive logic programming (DLP) have also been investigated. Inoue et al. [83] in particular, translate ALP clauses of the form
\[
p \leftarrow q, a
\]
where \( a \) is abducible, into DLP clauses
\[
(p \land a) \lor a' \leftarrow q
\]
where \( a' \) is a new atom that stands for the complement of \( a \), as expressed by the integrity constraint
\[
\neg(a \land a').
\] (3)
A model generation theorem-prover (such as SATCHMO or MGTP [88]) can then be applied to compute all the minimal models that satisfy the integrity constraints (3). This transformation is related to a similar transformation [82] for eliminating NAF.

Elsewhere [167], Sakama and Inoue demonstrate a one-to-one correspondence between generalised stable models for ALP and possible models [166] for DLP. Consider, for example, the abductive logic program \( \langle P; A; I \rangle \) where \( P \) is
\[
p \leftarrow a
\]
\( A = \{a\} \) and \( I \) is empty. \( M_1 = \emptyset \) and \( M_2 = \{a, p\} \) are the generalised stable models of \( \langle P; A; I \rangle \). The program can be transformed into a disjunctive logic program \( P_0 \)
\[
p \leftarrow a
\]
\( a \lor c.\)

\( P_0 \) has possible models \( M'_1 = \{c\}, M'_2 = \{a, p\} \) and \( M'_3 = \{c, a, p\} \), such that \( M'_1 - \{c\} = M_1 \) and \( M'_2 - \{c\} = M_2 \) and \( M'_3 - \{c\} = M_3 \).

Conversely, [167] shows how to transform DLP programs into ALP. For example, consider the disjunctive logic program \( P_0 \)
\[
a \lor b \leftarrow c
\]
\( c \)
whose possible models are \( M_1 = \{c, a\}, M_2 = \{c, b\} \) and \( M_3 = \{c, a, b\} \). It can be transformed into an abductive logic program \( \langle P; A; I \rangle \) where \( P \) consists of
\[
a \leftarrow c, a'
b \leftarrow c, b'
c
\]
\( a' \) and \( b' \) are new atoms, \( A = \{a', b'\} \), and \( I \) consists of
\[
\neg[c \land a] \land b.
\]
\( \langle P; A; I \rangle \) has generalised stable models \( M'_1 = \{c, a, a'\}, M'_2 = \{c, b, b'\} \) and \( M'_3 = \{c, a, a', b, b'\} \), such that, if \( HB \) is the Herbrand base of \( P_2, M_i \cap HB = M_i \) for each \( i = 1, 2, 3 \).

\( ^{19} \) A description of this work can also be found in [170].
Whereas the transformation of [167] deals with inclusive disjunction, Dung [41] presents a simpler transformation that deals with exclusive disjunction, but works only for the case of acyclic programs. For example, the clause
\[ p \lor q \]
can be replaced by the two clauses
\[ p \iff \neg q \]
\[ q \iff \neg p. \]

With this transformation, for acyclic programs, the Eshghi-Kowalski procedure presented in section 4.2 is sound. For the more general case, Dung [12] represents disjunction explicitly and extends the Eshghi-Kowalski procedure by using resolution-based techniques similar to those employed in [57].

5.6 Abduction through deduction from the completion

In the approaches presented so far, hypotheses are generated by backward reasoning with the clauses of logic programs used as inference rules. An alternative approach is presented by Console, Dupré and Torasso [26]. Here clauses of programs are interpreted as if-half of if-and-only-if definitions that are obtained from the completion of the program [22] restricted to non-abducible predicates. Abductive hypotheses are generated deductively by replacing atoms by their definitions, starting from the observation to be explained.

Given a propositional logic program \( P \) with abducible predicates \( A \) without definitions in \( P \), let \( P_C \) denote the completion of the non-abducible predicates in \( P \). An explanation formula for an observation \( O \) is the most specific formula \( F \) such that
\[
\exists \Delta \quad F \land \Delta \models O,
\]
where \( F \) is formulated in terms of abducible predicates only, and \( F \) is more specific than \( F' \) if \( \models F \Rightarrow F' \) and \( \not\models F' \Rightarrow F \).

Based on this specification, a proof procedure that generates explanation formulas is defined. This proof procedure replaces atoms by their definitions in \( P_C \), starting from a given observation \( O \). Termination and soundness of the proof procedure are ensured for hierarchical programs. The explanation formula resulting from the computation characterises all the different abductive explanations for \( O \), as exemplified in the following example.

Example 5.12
Consider the following program \( P \)
\[
\begin{align*}
\text{wobbly-wheel} & \leftarrow \text{broken-spokes} \\
\text{wobbly-wheel} & \leftarrow \text{flat-tyre} \\
\text{flat-tyre} & \leftarrow \text{punctured-tube} \\
\text{flat-tyre} & \leftarrow \text{leaky-valve},
\end{align*}
\]
where the predicates without definitions are considered to be abducible. The completion \( P_C \) is
\[
\begin{align*}
\text{wobbly-wheel} & \leftarrow \text{broken-spokes} \lor \text{flat-tyre} \\
\text{flat-tyre} & \leftarrow \text{punctured-tube} \lor \text{leaky-valve}.
\end{align*}
\]

If \( O \) is \text{wobbly-wheel} then the most specific explanation \( F \) is
\[
\text{broken-spokes} \lor \text{punctured-tube} \lor \text{leaky-valve},
\]
corresponding to the abductive explanations
\[
\begin{align*}
\Delta_1 & = \{\text{broken-spokes}\}, \\
\Delta_2 & = \{\text{punctured-tube}\}, \\
\Delta_3 & = \{\text{leaky-valve}\}.
\end{align*}
\]

Console, Dupré and Torasso extend this approach to deal with propositional abductive logic programs with integrity constraints \( I \) in the form of denials of abducibles and of clauses expressing taxonomic relationships among abducibles. An explanation formula for an observation \( O \) is now defined to be the most specific formula \( F \), formulated in terms of abducible predicates only, such that
\[
P_C \cup I \cup \{O\} \models F.
\]
The proof procedure is extended by using the denial and taxonomic integrity constraints to simplify \( F \).

In the more general case of non-propositional abductive logic programs, the Clark equality theory CET [24], is used; the notion that \( F \) is more specific than \( F' \) requires that \( F \Rightarrow \neg F' \) be a logical consequence of CET and that \( F' \Rightarrow \neg F \) not be a consequence of CET. The explanation formula is unique up to equivalence with respect to CET. The proof procedure is extended to take into account the equality theory CET.

Denencker and De Schreye [33] compare the search space obtained by reasoning backward using the if-half of the if-and-only-if form of a definite program with that obtained by reasoning forward using the only-if-half. They show an equivalence between the search space for SLD-resolution extended with abduction and the search space for model generation with SATCHMO [122] augmented with term rewriting to simulate unification.

5.7 Abduction and Constraint Logic Programming

ALP has many similarities with constraint logic programming (CLP). Recognition of these similarities has motivated a number of recent proposals to unify the two frameworks. Both frameworks distinguish two kinds of predicates. The first kind is defined by ordinary LP clauses, and is eliminated during query evaluation. The second kind is "constrained", either by integrity constraints in the case of ALP or by means of a built-in semantic domain in the case of CLP. In both cases, an answer to a query is a "satisfiable" formula.
involving only the second kind of predicate.

Certain predicates, such as inequality, can be treated either as abducible or as constraint predicates. Treated as abducible, they are constrained by explicitly formulated integrity constraints such as

\[ X < Z, \ Z < Y \rightarrow X < Y \]

\[ \neg [X < Y \land Y < X] \]

Treated as constraint predicates, they are tested for satisfiability by using specialised algorithms which respect the semantics of the underlying domain. Constraints can also be simplified, replacing, for example,

\[ 2 < t \land 3 < t \]

by

\[ 3 < t \]

Such simplification is less common in abductive frameworks.

A number of proposals have been made recently to unify the treatment of abducible and constraint predicates. Several of these, [50, 136, 120, 100] in particular, have investigated the implementation of specialised constraint satisfaction and simplification algorithms of CLP (specifically for inequality) by means of general-purpose integrity checking methods applied to domain-specific integrity constraints as in the case of ALP.

Kowalski [109] proposes a general framework which attempts to unify ALP and CLP using if-and-only-if definitions for ordinary LP predicates and using integrity constraints for abducible and constraint predicates. Abduction is performed by means of deduction in the style of [26] (see section 5.6). This framework has been developed further by Fung [60] and has been applied to job-shop scheduling by Toni [184]. A related proposal, to include user-defined constraint handling rules within a CLP framework, has been made by Frühwirth [75].

Bürchert [18] and Bürchert and Nutt [19], on the other hand, define a framework for general clausal resolution and show how abduction without integrity constraints can be treated as a special case of constrained resolution.

Another approach, which integrates both frameworks while preserving their identity, has been developed by Kakas and Michael [101]. In this approach, the central notions of the two frameworks are combined, so that abduction and constraint handling cooperate to solve a common goal. Typically, the goal is reduced first by abduction to abducible hypotheses whose integrity checking reduces this further to a set of constraints to be satisfied in CLP.

Constructive abduction is the generation of non-ground abductive explanations, such as \( \Delta = \{ Xa(X) \} \). The integrity checking of such abducible hypotheses involves the introduction of equality assumptions, which can naturally be understood in CLP terms. A procedure for performing constructive abduction within a framework that treats equality as an abducible predicate and the Clark equality theory as a set of integrity constraints was first proposed by Estghii [50]. Building upon this proposal, Kakas and Mancaella [68] extend the abductive proof procedure for LP in [54] (see section 4.2) to combine constructive negation with constructive abduction in a uniform way, by reducing the former to the latter using the abductive interpretation of NAF.

The problem of constructive abduction has also been studied within the completion semantics. Dencker and De Schreye [34] define a proof procedure for constructive abduction, SLDNA, for constructive negation to perform constructive abduction and be simplified, replacing, for example,\( \forall \) and \( \exists \) in integrity constraints are dealt with by means of a transformation, rather than explicitly.

### 6 Extended Logic Programming

Extended Logic Programming (ELP) extends general LP by allowing, in addition to NAF, a second, explicit form of negation, Explicit negation can be used when the definition of a predicate is incomplete, to explicitly define negative instances of the predicate, instead of having them inferred implicitly using NAF.

Clauses with explicit negation in their conclusions can also serve a similar function to integrity constraints with retractibles. For example, the integrity constraint

\[ \neg [\text{persists}(T_1, P, T_2) \land \text{happens}(E, T) \land \text{terminates}(E, P) \land T_1 \leq T \leq T_2] \]

with \( \text{persists}(T_1, P, T_2) \) retractible can be reformulated as a clause with explicit negation in the conclusion

\[ \neg \text{persists}(T_1, P, T_2) \leftarrow \text{happens}(E, T), \text{terminates}(E, P), T_1 \leq T \leq T_2. \]

### 6.1 Answer set semantics

In general logic programs, negative information is inferred by means of NAF. This is appropriate when the closed world assumption [157], that the program gives a complete definition of the positive instances of a predicate, can safely be applied. It is not appropriate when the definition of a predicate is incomplete and therefore "open", as in the case of abducible predicates.

For open predicates it is possible to extend logic programs to allow explicit negation in the conclusions of clauses. In this section we will discuss the extension proposed by Gelfond and Lifschitz [69]. This extension is based on the stable model semantics, and can be understood, therefore, in terms of abduction, as we have already seen.

Gelfond and Lifschitz define the notion of extended logic programs, consisting of clauses of the form

\[ L_0 \leftarrow L_1, \ldots, L_m, \sim L_{m+1}, \ldots, \sim L_n \]
where \( n \geq m \geq 0 \) and each \( L_i \) is either an atom \((A)\) or the explicit negation of an atom \((\neg A)\). This negation denoted by \( \sim \) is called “classical negation” in [69]. However, as we will see below, because the contrapositives of extended clauses do not hold, the term “classical negation” can be regarded as inappropriate. For this reason we use the term “explicit negation” instead.

A similar notion has been investigated by Pearce and Wagner [130], who develop an extension of definite programs by means of Nelson’s strong negation. They also suggest the possibility of combining strong negation with NAF. Akama [1] argues that the semantics of this combination of strong negation with NAF is equivalent to the answer set semantics for extended logic programs developed by Gelfond and Lifschitz.

The semantics of an extended program is given by its answer sets, which are like stable models but consist of both positive and (explicit) negative literals. Perhaps the easiest way to understand the semantics is to transform the extended program \( P \) into a general logic program \( P' \) without explicit negation, and to apply the stable model semantics to the resulting general logic program. The transformation consists in replacing every occurrence of explicit negation \( \neg p(t) \) by a new (positive) atom \( p'(t) \). The stable models of \( P' \) which do not contain a contradiction of the form \( p(t) \) and \( p'(t) \) correspond to the consistent answer sets of \( P \). The corresponding answer sets of \( P \) contain explicit negative literals \( \neg p(t) \) wherever the stable models contain \( p'(t) \). In [69] the answer sets are defined directly on the extended program by modifying the definition of the stable model semantics. The consistent answer sets of \( P \) also correspond to the generalised stable models (see section 5.1) of \( P' \) with a set of integrity constraints \( \forall X \sim [p(X) \land p'(X)] \), for every predicate \( p \).

In the general case a stable model of \( P' \) might contain a contradiction of the form \( p(t) \) and \( p'(t) \). In this case the corresponding inconsistent answer set is defined to be the set of all the variable-free (positive and explicit negative) literals. It is in this sense that explicit negation can be said to be “classical”. The same effect can be obtained by explicitly augmenting \( P' \) by the clauses

\[
q(X) \leftarrow p(X), p'(X)
\]

for all predicate symbols \( q \) and \( p \) in \( P' \). Then the answer sets of \( P \) simply correspond to the stable models of the augmented set of clauses. If these clauses are not added, then the resulting treatment of explicit negation gives rise to a paraconsistent logic, i.e. one in which contradictions are tolerated.

Notice that, although Gelfond and Lifschitz define the answer set semantics directly without transforming the program and then applying the stable model semantics, the transformation can also be used with any other semantics for the resulting transformed program. Thus Przymusinski [153] for example applies the well-founded semantics to extended logic programs. Similarly any other semantics can also be applied. As we have seen before, this is one of the main advantages of transformational semantics in general.

An important problem for the practical use of extended programs is how to distinguish whether a negative condition is to be interpreted as explicit negation or as NAF. This problema will be addressed in sections 6.4 and 9.

6.2 Restoring consistency of answer sets

The answer sets of an extended program are not always consistent.

Example 6.1

The extended logic program:

\[
\neg fly(X) \leftarrow bird(X) \\
fly(X) \leftarrow bat(X) \\
bat(tom)
\]

has no consistent answer set.

As mentioned in section 6.1, this problem can be dealt with by employing a paraconsistent semantics. Alternatively, in some cases it is possible to restore consistency by removing some of the NAF assumptions implicit in the answer set. In the example above we can restore consistency by rejecting the NAF assumption \( \neg bird(tom) \) even though \( \neg bird(tom) \) does not hold. We then get the consistent set \{bat(tom), fly(tom)\}. This problem has been studied in [46] and [137]. Both of these studies are primarily concerned with the related problem of inconsistency of the well-founded semantics when applied to extended logic programs [153].

To deal with the problem of inconsistency in extended logic programs, Dung and Thiemann [46] apply the preferred extension semantics to a new abductive framework derived from an extended logic program. An extended logic program \( P \) is first transformed into an ordinary general logic program \( P' \) by renaming explicitly negated literals \( \neg p(t) \) by positive literals \( p'(t) \). The resulting program is then further transformed into an abductive framework by renaming NAF literals \( \neg q(t) \) by positive literals \( q'(t) \) and adding the integrity constraints

\[
\forall X \sim [q(X) \land q'(X)]
\]

as described in section 4.3. Thus if \( p' \) expresses the explicit negation of \( p \) the set \( A' \) will contain \( p'^* \) as well as \( p' \). Moreover Dung includes in \( P' \) additional integrity constraints of the form

\[
\forall X \sim [p(X) \land p'(X)]
\]

to prevent contradictions.

Extended preferred extensions are then defined by modifying the definition of preferred extensions in section 4 for the resulting abductive framework with this new set \( I' \) of integrity constraints. The new integrity constraints in \( P' \) have the effect of removing a NAF hypothesis when it leads to a contradiction. Clearly, any other semantics for logic programs with integrity constraints could also be applied to this framework.

Pereira, Apt and Alfeires [137] employ a similar approach within the context of Przymusinski’s extended stable models [153]. It consists in identifying explicitly all the
The semantics is given using abduction as in [145] (see section 3) by means of theory extensions \( P \cup \Delta \) of \( P \), with \( \Delta \subseteq H \) maximal with respect to set inclusion, such that \( P \cup \Delta \) has a consistent answer set.

In this approach, whenever the answer set of an extended logic program \( P \) is inconsistent, it is possible to restore consistency by regarding it as a knowledge system of the form 

\[
(\emptyset, P)
\]

For example 6.3 this will give two alternative semantics, \{ \( p \) \} or \{ \( \neg p \) \}.

A similar approach to restoring consistency follows also from the work in [87, 99] (see section 7), where argumentation-based semantics can be used to select acceptable (and hence consistent) subsets of an inconsistent extended logic program.

### 6.3 Rules and exceptions in LP

Another way of restoring consistency of answer sets is presented in [112], where sentences with explicitly negated conclusions are given priority over sentences with positive conclusions. In this approach, extended clauses with negative conclusions are similar to integrity constraints with retractibles.

**Example 6.4**

Consider the program

\[
\begin{align*}
\text{fly}(X) & \leftarrow \text{bird}(X) \\
\text{walk}(X) & \leftarrow \text{ostrich}(X) \\
\text{bird}(X) & \leftarrow \text{ostrich}(X) \\
\text{ostrich}(X) & \leftarrow \text{john}(X)
\end{align*}
\]

and the integrity constraint

\[
\neg (\text{fly}(X) \land \text{walk}(X)),
\]

with \( \text{fly}(X) \) retractable. The integrity constraint is violated, because both \( \text{walk}(X) \) and \( \text{fly}(X) \) hold. Following the approach presented in section 5.3, integrity can be restored by retracting the instance

\[
\text{fly}(\text{john}) \leftarrow \text{bird}(\text{john})
\]

of the first clause in the program. Alternatively, the integrity constraint can be formulated as a clause with an explicit negative conclusion

\[
\neg \text{fly}(X) \leftarrow \text{walk}(X)
\]

In the new formulation it is natural to interpret clauses with negative conclusions as exceptions, and clauses with positive conclusions as default rules. In this example, the extended clause

\[
\neg \text{fly}(X) \leftarrow \text{walk}(X)
\]
can be interpreted as an exception to the “general” rule
\[ \text{fly}(X) \leftarrow \text{bird}(X). \]

To capture the intention that exceptions should override general rules, Kowalski and Sadri [112] modify the answer set semantics, so that instances of clauses with positive conclusions are retracted if they are contradicted by explicit negative information.

Kowalski and Sadri [112] also present a transformation, which preserves the new semantics, and is arguably a more elegant form of the transformation presented in [111] (see section 5.5). In the case of the flying-birds example described above the new transformation gives the clause
\[ \text{fly}(X) \leftarrow \text{bird}(X), \sim \sim \text{fly}(X). \]

This can be further transformed by “macroprocessing” the call to \(\sim \sim \text{fly}(X)\), giving the result of the original transformation in [111]
\[ \text{fly}(X) \leftarrow \text{bird}(X), \sim \text{walk}(X). \]

In general, the new transformation introduces a new condition
\[ \sim \sim p(t) \]
into every clause with a positive conclusion \(p(t)\). The condition is vacuous if there are no exceptions with \(\sim p\) in the conclusion. The answer set semantics of the new program is equivalent to the modified answer set semantics of the original program, and both are consistent. Moreover, the transformed program can be further transformed into a general logic program by renaming explicit negations \(\sim p\) by new positive predicates \(p'\). Because this renaming, positive and negative predicates can be handled symmetrically, and therefore, in effect, clauses with positive conclusions can represent exceptions to rules with (renamed) negative conclusions. Thus, for example, a negative rule such as
\[ \sim \sim \text{fly}(X) \leftarrow \text{walk}(X) \]
with a positive exception
\[ \text{fly}(X) \leftarrow \text{super\ ostrich}(X) \]
can be transformed into a clause
\[ \sim \sim \text{fly}(X) \leftarrow \text{walk}(X), \sim \text{fly}(X) \]
and all occurrences of the negative literal \(\sim \text{fly}(X)\) can be renamed by a new positive literal \(\sim \text{fly}(X)\). This is not entirely adequate for a proper treatment of exceptions to exceptions. However, this approach can be extended, as we shall see in section 6.6.

More direct approaches to the problem of treating positive and negative predicates symmetrically in default reasoning are presented in [81, 80], following the methods of [66] and [145] (see section 6.2 for a discussion), and in [87, 99], based on an argumentation-theoretic framework (see sections 6.4 and 7).

6.4 (Extended) Logic Programming without Negation as Failure

Kakas, Mancarella and Dung [99] show that the Kowalski-Sadri transformation presented in section 6.3 can be applied in the reverse direction, to replace clauses with NAF by clauses with explicit negation together with a priority ordering between extended clauses. Thus, for example,
\[ \text{fly}(X) \leftarrow \text{bird}(X), \sim \text{walk}(X) \]
can be transformed “back” to
\[ \text{fly}(X) \leftarrow \text{bird}(X) \]
\[ \sim \text{fly}(X) \leftarrow \text{walk}(X) \]
together with an ordering that indicates that the second clause has priority over the first.

In general, the extended clauses
\[ r_1 : \sim p \leftarrow s_1 \]
\[ r_k : \sim p \leftarrow s_k \]
generated by transforming the clause
\[ p \leftarrow q_1 \ldots q_n \sim s_1 \ldots \sim s_k \]
are ordered so that \(r_j > r_k\) for \(1 \leq j \leq k\). In [99], the resulting prioritised clauses are formulated in an ELP framework (with explicit negation) without NAF but with an ordering relation on the clauses of the given program.

This new framework for ELP is proposed in [99] as an example of a general theory of the acceptability semantics (see section 4.3) developed within the argumentation-theoretic framework introduced in [88] (see section 7). Its semantics is based upon an appropriate notion of attack between subtheories consisting of partially ordered extended clauses in a theory \(T\). Informally, for any subsets \(E\) and \(\Delta\) of \(T\) such that \(E \cup \Delta\) have a contradictory consequence, \(E\) attacks \(\Delta\) if and only if either \(E\) does not contain a clause which is lower than some clause in \(\Delta\) or if \(E\) does contain such a clause, it also contains some clause which is higher than a clause in \(\Delta\). Thus, the priority ordering is used to break the symmetry between the incompatible sets \(E\) and \(\Delta\). Hence in the example above, if we have a bird that walks, then the subtheory which, in addition to these two facts, consists of the second clause
\[ \sim \text{fly}(X) \leftarrow \text{walk}(X) \]
attacks the subtheory consisting of the clause
\[ \text{fly}(X) \leftarrow \text{bird}(X) \]
and the same two facts, but not vice versa, so the first subtheory is acceptable whereas the second one is not.
Kakas, Mancarella and Dung show that, with this notion of attack in the new framework with explicit negation but without NAF, it is possible to capture exactly the semantics of NAF in LP. This shows that, if LP is extended with explicit negation, then NAF can be simulated by introducing a priority ordering between clauses. Moreover, the new framework of ELP is more general than conventional ELP as it allows any ordering relation on the clauses of extended logic programs.

In the extended logic program which results from the transformation described above, if \( \neg p \) holds then \( \sim p \) holds in the corresponding general logic program, for any atom \( p \). We can argue, therefore, that the transformed extended logic program satisfies the coherence principle, proposed by Pereira and Alferes [135], namely that whenever \( \neg p \) holds then \( \sim p \) must also hold. They consider the satisfaction of this principle to be a desirable property of any semantics for ELP, as illustrated by the following example, taken from [3].

**Example 6.5**

Given the extended logic program

\[
\begin{align*}
\neg \text{drivers\_strike} \\
\text{take\_has} & \leftarrow \neg \text{drivers\_strike}
\end{align*}
\]

one should derive the conclusion \( \text{take\_has} \).

The coherence principle automatically holds for the answer set semantics. Pereira and Alferes [135] and Alferes, Dung and Pereira [2] have defined new semantics for ELP that incorporates the coherence principle. These semantics are adaptations of Przymusznysz’s extended stable model semantics [153] and Dung’s preferred extension semantics [39], respectively, to ELP. Alferes, Damasio and Pereira [2] provide a sound and complete proof procedure for the semantics in [135]. The proof procedure is implemented in Prolog by means of an appropriate transformation from ELP to general LP.

### 6.5 An argumentation-theoretic approach to ELP

The Dung and Ruan–Boonsuk semantics for ELP [16] in effect reduces ELP to ALP by renaming the explicit negation \( \neg p \) of a predicate \( p \) to a new predicate \( p’ \) and employing integrity constraints

\[
\forall X \quad [p(X) \land p'(X)]
\]

for all predicates \( p \) in the program. This reduction automatically provides us with an argumentation-theoretic interpretation of ELP, where attacks via these integrity constraints become attacks via explicit negation. Such notions of attack via explicit negation have been defined by Dung [15] and Kakas, Mancarella and Dung [99]. Dung’s notion can be formulated as follows: a set of NAF literals \( E \) attacks another such set \( \Delta \) via explicit negation (relative to a program \( P^\prime \)) \footnote{Note that, for simplicity, here we use NAF literals directly as hypotheses, without renaming them as positive atoms.} if

\[
\begin{align*}
& P \cup E \cup \Delta \vdash p, p', \text{ for some atom } p, \\
& P \cup E \vdash p, p', \text{ and } P \cup \Delta \not\vdash p, \text{ for all atoms } p.
\end{align*}
\]

Kakas, Mancarella and Dung’s notion can be formulated as follows: \( E \) attacks a non-empty set \( \Delta \) via explicit negation (relative to a program \( P^\prime \)) if

\[
\begin{align*}
& P^\prime \cup E \vdash l \land P^\prime \cup \Delta \not\vdash \overline{l}, \text{ for some literal } l,
\end{align*}
\]

where \( \overline{l} = p’ \) and \( \overline{p} = p \).

Augmenting the notion of attack via NAF by either of these new notions of attack via explicit negation, we can define admissibility, weak stability and acceptability semantics similarly to the definitions in section 4.3. However, the resulting semantics might give unwanted results, as illustrated by the following example given in [15].

**Example 6.6**

Given the extended logic program

\[
\begin{align*}
\text{fly}(X) & \leftarrow \text{bird}(X), \neg \text{ab\_bird}(X) \\
\neg \text{fly}(X) & \leftarrow \text{penguin}(X), \neg \text{ab\_penguin}(X) \\
\text{bird}(X) & \leftarrow \text{penguin}(X) \\
\text{penguin}(\text{twetty}) & \\
\text{ab\_bird}(X) & \leftarrow \text{penguin}(X), \neg \text{ab\_penguin}(X)
\end{align*}
\]

\{\text{ab\_penguin}(\text{twetty})\} attacks \{\text{ab\_bird}(\text{twetty})\} via NAF. However, \{\text{ab\_bird}(\text{twetty})\} attacks \{\text{ab\_penguin}(\text{twetty})\} via explicit negation (and vice versa). Therefore, \{\text{ab\_bird}(\text{twetty})\} counterattacks all attacks against it, and is admissible. As a consequence, \text{fly}(\text{twetty}) holds in the extension given by \{\text{ab\_bird}(\text{twetty})\}. However, intuitively \text{fly}(\text{twetty}) should hold in no extension.

To cope with this problem, Dung [15] suggests the following semantics, while keeping the definition of attack unchanged. A set of hypotheses is **D-admissible** if

- \( \Delta \) does not attack itself, either via explicit negation or via NAF,

- for every attack \( E \) against \( \Delta \), either via explicit negation or via NAF, \( E \) attacks \( \Delta \) via NAF.

Note that, if ELP is seen as a special instance of ALP, then D-admissibility is very similar to KM-admissibility, presented in section 5.3 for ALP, in that the two notions share the feature that counterattacks can only be provided by means of attacks via NAF.

It can be argued, however, that the problem in this example lies not so much with the semantics but with the representation itself. The last clause

\[
\text{ab\_bird}(X) \leftarrow \text{penguin}(X), \neg \text{ab\_penguin}(X)
\]

can be understood as attempting to assign a higher priority to the second clause of the program over the first. This can be done, without this last clause, explicitly in the ELP framework with priorities of [99] (section 6.4) or in the rules and exceptions approach.
An argumentation-theoretic interpretation for ELP has also been proposed by Bondarenko, Toni and Kowalski [11]. Their proposal, which requires that \( \mathcal{F} \cup \Delta \) be consistent with the integrity constraints
\[
\forall X \neg [p(X) \land \neg q(X)]
\]
for each predicate \( p \), instead of using a separate notion of attack via explicit negation, has certain undesirable consequences, as shown in [4]. For example, the program
\[
p \leftarrow q, \neg q
\]
admits both \( \{
eg q \} \) and \( \{\neg p\} \) as admissible extensions, while the only intuitively correct extension is \( \{\neg q\} \).

Allt and Bondarenko [9] also define a well-founded semantics for ELP based upon argumentation-theoretic notions.

### 6.6 A methodology for default reasoning with explicit negation

Compared with other authors, who primarily focus on extending or modifying the semantics of LP to deal with default reasoning, Pereira, Aparicio and Alferes [136] develop a methodology for performing default reasoning with extended logic programs. Defaults of the form “normally if \( p \) then \( p' \)” are represented by an extended clause
\[
p \leftarrow q, \neg \text{nameeq}, \neg p
\]
where the condition \( \text{nameeq} \) can be understood as a name given to the default. The condition \( \neg p \) deals with exceptions to the conclusion of the rule, whilst the condition \( \neg \text{nameeq} \) deals with exceptions to the rule itself. An exception to the rule would be represented by an extended clause of the form
\[
\neg \text{nameeq} \leftarrow r
\]
where the condition \( r \) represents the conditions under which the exception holds. In the flying-birds example, the second clause of
\[
\text{fly}(X) \leftarrow \text{bird}(X), \neg \text{bird}\_\text{fly}, \neg \text{fly}(X)
\]
expresses that the default named \( \text{bird}\_\text{fly} \) does not apply for penguins.

The possibility of expressing both exceptions to rules as well as exceptions to predicates is useful for representing hierarchies of exceptions. Suppose we want to change (6) to the default rule “penguins usually don’t fly”. This can be done by replacing (6) by
\[
\neg \text{fly}(X) \leftarrow \text{penguin}(X), \neg \text{penguins}\_\text{don’t}\_\text{fly}(X), \neg \text{fly}(X)
\]
where \( \text{penguins}\_\text{don’t}\_\text{fly} \) is the name assigned to the new rule. To give preference to the more specific default represented by (7) over the more general default (5), we add the additional clause
\[
\neg \text{birds}\_\text{fly}(X) \leftarrow \text{penguin}(X), \neg \text{penguins}\_\text{don’t}\_\text{fly}(X).
\]

Then to express that super-penguins fly, we can add the rule:
\[
\neg \text{penguins}\_\text{don’t}\_\text{fly}(X) \leftarrow \text{super-penguin}(X).
\]

Pereira, Aparicio and Alferes [136] use the well-founded semantics extended with explicit negation to give a semantics for this methodology for default reasoning. However it is worth noting that any other semantics of extended logic programs could also be used. For example Inoue [81, 80] uses an extension of the answer set semantics (see section 6.2), but for a slightly different transformation.

#### 6.7 ELP with abduction

Inoue [80] (see also section 6.3) and Pereira, Aparicio and Alferes [136] investigate extended logic programs with abducibles but without integrity constraints. They transform such programs into extended logic programs without abduction by adding a new pair of clauses
\[
p(X) \leftarrow \neg p(X)
\]
\[
\neg p(X) \leftarrow \neg p(X)
\]
for each abducible predicate \( p \). Notice that the transformation is identical to that of Satoh and Inoue [170] presented in section 5.5, except for the use of explicit negation instead of new predicates. Inoue [80] and Pereira, Aparicio and Alferes [136] assign different semantics to the resulting program. Whereas Inoue applies the answer set semantics, Pereira, Aparicio and Alferes apply the extended stable model semantics of [153]. Pereira, Aparicio and Alferes [136] have also developed proof procedures for this semantics.

As mentioned above, Pereira, Aparicio and Alferes [136] understand the transformed programs in terms of (three-valued) extended stable models. This has the advantage that it gives a semantics to every logic program and it does not force abducibles to be either believed or disbelieved. But the advantage of the transformational approach, as we have already remarked, is that the semantics of the transformed program is independent of the transformation. Any semantics can be used for the transformed program (including an even a transformational one, e.g. replacing explicitly negated atoms \( \neg p(l) \) by a new atom \( p'(l) \)).

#### 7 An Abstract Argumentation-based Framework for Default Reasoning

Following the argumentation-theoretic interpretation of NAF introduced in [88], Kakas [87] generalised the interpretation and showed how other logics for default reasoning can
For non-monotonic logic, the theory \( T \) is any set of sentences written in modal logic, and usually \( T \) is monotonous, as in the case of autoepistemic logic. The probability \( \text{P}(\Delta \mid T) \) of \( \Delta \) can be regarded as the probabilistic semantics of the homogeneous extension, which is obtained as approximations of the acceptability semantics. A sceptical form of a sceptical logic program, based on a stronger form of acceptability, ensures that defeasible arguments are constructed, i.e., that they do not at the same time attack the theory that we are trying to construct.

For default logic, default rules are rewritten as sentences of the form

\[ \neg \Delta \land (\Delta \lor \Phi) \Rightarrow \Phi \]

This more general notion is useful for capturing the semantics of an argumentation framework.
Because this framework does not separate the theory into facts and candidate assumptions, the attacking relation would be symmetric. To avoid this, a priority relation can be given on the sentences of the theory. As an example of this approach, Kakas, Mancarella and Dung propose a framework for ELP where programs are accompanied by a priority ordering on their clauses and show how in this framework NAF can be removed from the object-level language (see also section 6.1). More generally, this approach provides a framework for default reasoning with priorities on sentences of a theory, viewed as default rules. It also provides a framework for restoring consistency in a theory \( T \) by using the acceptable subsets of \( T \) (see sections 6.2 and 6.3).

Brewka and Konolige [15] also propose an abductive framework which unifies and provides new semantics for LP, autoepistemic logic and default logic, but does not use argumentation-theoretic notions. This semantics generalises the semantics for LP given in [14].

8 Abduction and Truth Maintenance

In this section we will consider the relationship between truth maintenance (TM) and abduction. TM systems have historically been presented from a procedural point of view. However, we will be concerned primarily with the semantics of TM systems and the relationship to the semantics of abductive logic programming.

A TM system is part of an overall reasoning system which consists of two components: a domain dependent problem solver which performs inferences and a domain independent TM system which records these inferences. Inferences are communicated to the TM system by means of justifications, which in the simplest case can be written in the form

\[ p \leftarrow p_1, \ldots, p_n \]

expressing that the proposition \( p \) can be derived from the propositions \( p_1, \ldots, p_n \). Justifications include premises, in the case \( n = 0 \), representing propositions which hold in all contexts. Propositions can depend upon assumptions which vary from context to context.

TM systems can also record nogoods, which can be written in the form

\[ \neg \{ p_1, \ldots, p_n \} \]

meaning that the propositions \( p_1, \ldots, p_n \) are incompatible and therefore cannot hold together.

Given a set of justifications and nogoods, the task of a TM system is to determine which propositions can be derived on the basis of the justifications, without violating the nogoods.

For any such TM system there is a straight-forward correspondence with abductive logic programs

- justifications correspond to propositional Horn clause programs,
- nogoods correspond to propositional integrity constraints,
- assumptions correspond to abducible hypotheses, and
- contexts correspond to acceptable sets of hypotheses.

The semantics of a TM system can accordingly be understood in terms of the semantics of the corresponding propositional logic program with abducibles and integrity constraints.

The two most popular systems are the justification-based TM system (JTMS) of Doyle [30] and the assumption-based TM system (ATMS) of deKleer [102].

8.1 Justification-based truth maintenance

A justification in a JTMS can be written in the form

\[ p \leftarrow p_1, \ldots, p_n \sim \sim p_{n+1}, \ldots, \sim p_m, \]

expressing that \( p \) can be derived (i.e., is IN in the current set of beliefs) if \( p_1, \ldots, p_n \) can be derived (are IN) and \( p_{n+1}, \ldots, p_m \) cannot be derived (are OUT).

For each proposition occurring in a set of justifications, the JTMS determines an IN or OUT label, taking care to avoid circular arguments and thus ensuring that each proposition which is labelled IN has well-founded support. The JTMS incrementally revises beliefs when a justification is added or deleted.

The JTMS uses nogoods to record contradictions discovered by the problem solver and to perform dependency-directed backtracking to change assumptions in order to restore consistency. In the JTMS changing an assumption is done by changing an OUT label to IN.

Suppose, for example, that we are given the justifications

\[ p \leftarrow \sim q \]

\[ q \leftarrow \sim r \]

corresponding to the propositional form of the Yale shooting problem. As Morris [127] observes, these correctly determine that \( q \) is labelled IN and that \( r \) and \( p \) are labelled OUT. If the JTMS is subsequently informed that \( p \) is true, then dependency-directed backtracking will install a justification for \( r \), changing its label from OUT to IN. Notice that this is similar to the behaviour of the extended abductive proof procedure described in example 5.5, section 5.2.

Several authors have observed that the JTMS can be given a semantics corresponding to the semantics of logic programs, by interpreting justifications as propositional logic program clauses, and interpreting \( \sim p \) as NAF of \( p \). The papers [49, 71, 92, 141], in particular, show that a well-founded labelling for a JTMS corresponds to a stable mode...
of the corresponding logic program. Several authors [49, 50, 92, 156], exploiting the interpretation of stable models as autoepistemic expansions [68], have shown a correspondence between well-founded labellings and stable expansions of the set of justifications viewed as autoepistemic theories.

The JTMS can also be understood in terms of abduction using the abductive approach to the semantics of NAF, as shown in [40, 71, 92]. This has the advantage that the nogoods of the JTMS can be interpreted as integrity constraints of the abductive framework. The correspondence between abduction and the JTMS is reinforced by [170], which gives a proof procedure to compute generalised stable models using the JTMS (see section 5.4).

8.2 Assumption-based truth maintenance
Justifications in ATMS have the more restricted Horn clause form

\[ p \leftarrow p_1, \ldots, p_n \]

However, whereas the JTMS maintains only one implicit context of assumptions at a time, the ATMS explicitly records with every proposition the different sets of assumptions which provide the foundations for its belief. In ATMS, assumptions are propositions that have been pre-specified as assumable. Each record of assumptions that supports a proposition \( p \) can also be expressed in Horn clause form

\[ p \leftarrow a_1, \ldots, a_n \]

and can be computed from the justifications, as we illustrate in the following example.

Example 8.1
Suppose that the ATMS contains justifications

\[
\begin{align*}
  p & \leftarrow a, b \\
  p & \leftarrow b, c, d \\
  q & \leftarrow a, c \\
  q & \leftarrow d, e
\end{align*}
\]

and the single nogood

\[ \neg (a, b, c) \]

where \( a, b, c, d, e \) are assumptions. Given the new justification

\[ r \leftarrow p, q \]

the ATMS computes explicit records of \( r \)'s dependence on the assumptions:

\[
\begin{align*}
  r & \leftarrow a, b, c \\
  r & \leftarrow b, c, d, e
\end{align*}
\]

The dependence

\[ r \leftarrow a, b, d, e \]

is not recorded because its assumptions violate the nogood. The dependence

\[ r \leftarrow a, b, c, d \]

is not recorded because it is subsumed by the dependence

\[ r \leftarrow a, b, c. \]

Reiter and deKleer [162] show that, given a set of justifications, nogoods, and candidate assumptions, the ATMS can be understood as computing minimal and consistent abductive explanations in the propositional case (where assumptions are interpreted as abductive hypotheses). This abductive interpretation of ATMS has been developed further by Inoue [93], who gives an abductive proof procedure for the ATMS.

Given an abductive logic program \( P \) and goal \( G \), the explicit construction in ALP of a set of hypotheses \( \Delta \), which together with \( P \) implies \( G \) and together with \( P \) satisfies any integrity constraints \( I \), is similar to the record computed by the ATMS. There are, however, some obvious differences. Whereas ATMS deals only with propositional justifications, relying on a separate problem solver to instantiate variables, ALP deals with general clauses, combining the functionalities of both a problem solver and a TM system.

The extension of the ATMS to the non-propositional case requires a new notion of minimality of sets of assumptions. Minimality as subset inclusion is not sufficient, but needs to be replaced by a notion of minimal consequence from sets of not necessarily variable-free assumptions [115].

Ignoring the propositional nature of a TM system, ALP can be regarded as a hybrid of JTMS and ATMS, combining the non-monotonic negative assumptions of JTMS and the positive assumptions of ATMS, and allowing both positive and negative conditions in both justifications and nogoods [92]. Other non-monotonic extensions of ATMS have been developed in [84, 163].

It should be noted that one difference between ATMS and ALP is the requirement in ATMS that only minimal sets of assumptions be recorded. This minimality of assumptions is essential for the computational efficiency of the ATMS. However, it is not essential for ALP, but can be imposed as an additional requirement when it is needed.

9 Conclusions and Future Work

In this paper we have surveyed a number of proposals for extending LP to perform abductive reasoning. We have seen that such extensions are closely linked with other extensions including NAF, integrity constraints, explicit negation, default reasoning, belief revision
Of special importance is the problem of relating circumscription and the if-then-else completion semantics to the argumentation-theoretic approach. An important step in this direction may be the "common-sense" axiomatisation of NAF [188] by Van Gelder and Shoham, which augments circumscription with axioms of induction. The inclusion of induction axioms relates this approach to circumscription, whereas the evolution of negation by new positive literals relates it to the abductive interpretation of NAF.

The development of systems that combine LP and CLP is another important area that is receiving much attention. These systems are being used to investigate the relationship between the semantics of NAF and the semantics of LP, as well as the relationship between the semantics of NAF and the semantics of CLP.

The use of default abduction for NAF is a special case of abduction in general. The distinction between default and non-default hypotheses is important in this context. The input is processed and transformed by a process that generates abduction hypotheses and tests them for consistency. Notice that the abduction procedure can be extended in turn to accommodate other abductive and other integrity constraints. It remains to be seen whether the efficiency of proof procedures for the acceptability semantics can be avoided in practice.

We have seen that abductive proof procedures for LP can be extended to NAF. We have also seen that abductive proof procedures for CLP can be extended in turn to accommodate other abductive and other integrity constraints. It remains to be seen whether the efficiency of proof procedures for the acceptability semantics can be avoided in practice.

The further development, clarification and simplification of the abstract argumentation-theoretic framework for NAF is needed to be considered within a KA framework. We have argued that the implementation of abduction needs to be based on combined two proof procedures: backward reasoning both to generate abduction hypotheses and to test whether existing information is redundant, and forward reasoning both to test input for consistency and to test whether existing information is redundant. Notice that the abduction procedure is still in its infancy. Among the results that might be expected from this development is an abstract framework for such an integration.

We have seen the importance of clarifying the semantics of abduction and of defining a common framework for such an integration. The abstraction-theoretic approach seems to offer a promising framework for such an integration. The abstraction-theoretic approach seems to offer a promising framework for such an integration.

The extension of LP to include integrity constraints is another important direction for future research. This will enable the use of default hypotheses for abductive databases, and the use of default hypotheses for abductive databases.
integrity constraints with retractibles can be replaced by clauses with explicitly negated conclusions with priorities. Moreover, the use of explicit negation with priorities seems to have several advantages, including the ability both to represent and derive negative information, as well as to obtain the effect of NAF.

The relationship between integrity constraints with retractibles and explicit negation with priorities needs to be investigated further. To what extent does this relationship, which holds for abduction and default reasoning, hold for other uses of integrity constraints, such as those employed in deductive databases, and what are the implications of this relationship on the semantics and implementation of integrity constraints?

We have remarked upon the close links between the semantics of LP with abduction and the semantics of truth maintenance systems. The practical consequences of these links, both for building applications and for efficient implementations, need further investigation. What is the significance, for example, of the fact that conventional TMSs and ATMSs correspond only to the propositional case of logic programs?

We have seen the rapid development of the abduction-based argumentation-theoretic approach to non-monotonic reasoning. But argumentation has wider applications in areas such as law and practical reasoning more generally. It would be useful to see to what extent the theory of argumentation might be extended to encompass such applications. It would be especially gratifying, in particular, if such an extended argumentation theory might be used, not only to understand how one argument can defeat another, but also to indicate how conflicting arguments might be reconciled.

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